

Dive into Deep Learning in 1 Day

1 Basics · 2 Convnets · 3 Computation · 4 Sequences

ODSC 2019

Alex Smola

<http://courses.d2l.ai/odsc2019/>

Outline

- Sequence models and language models
- Recurrent neural networks (RNN)
- GRU and LSTM
- Deep RNNs, Bi-RNNs

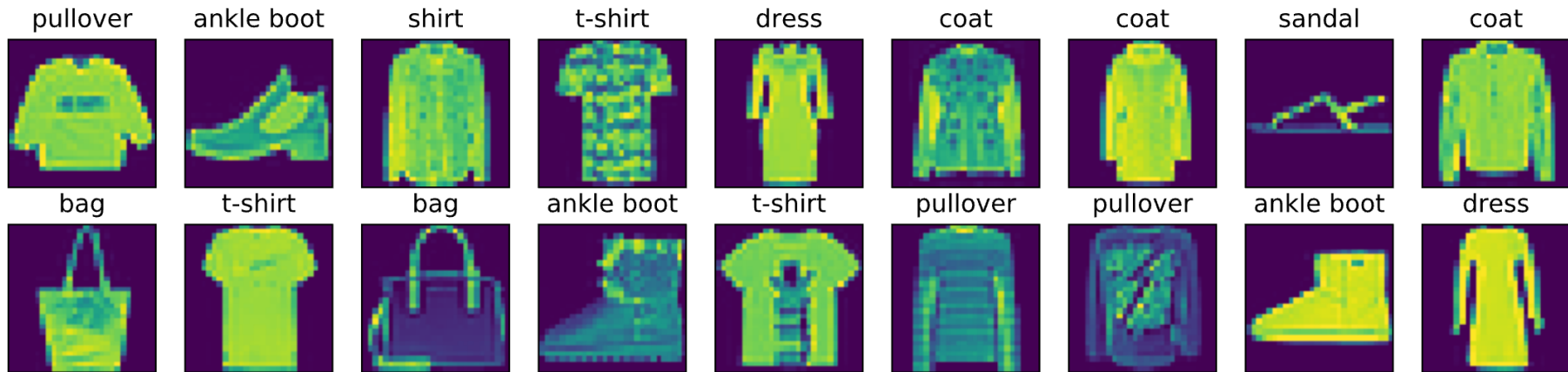
Dependent Random Variables



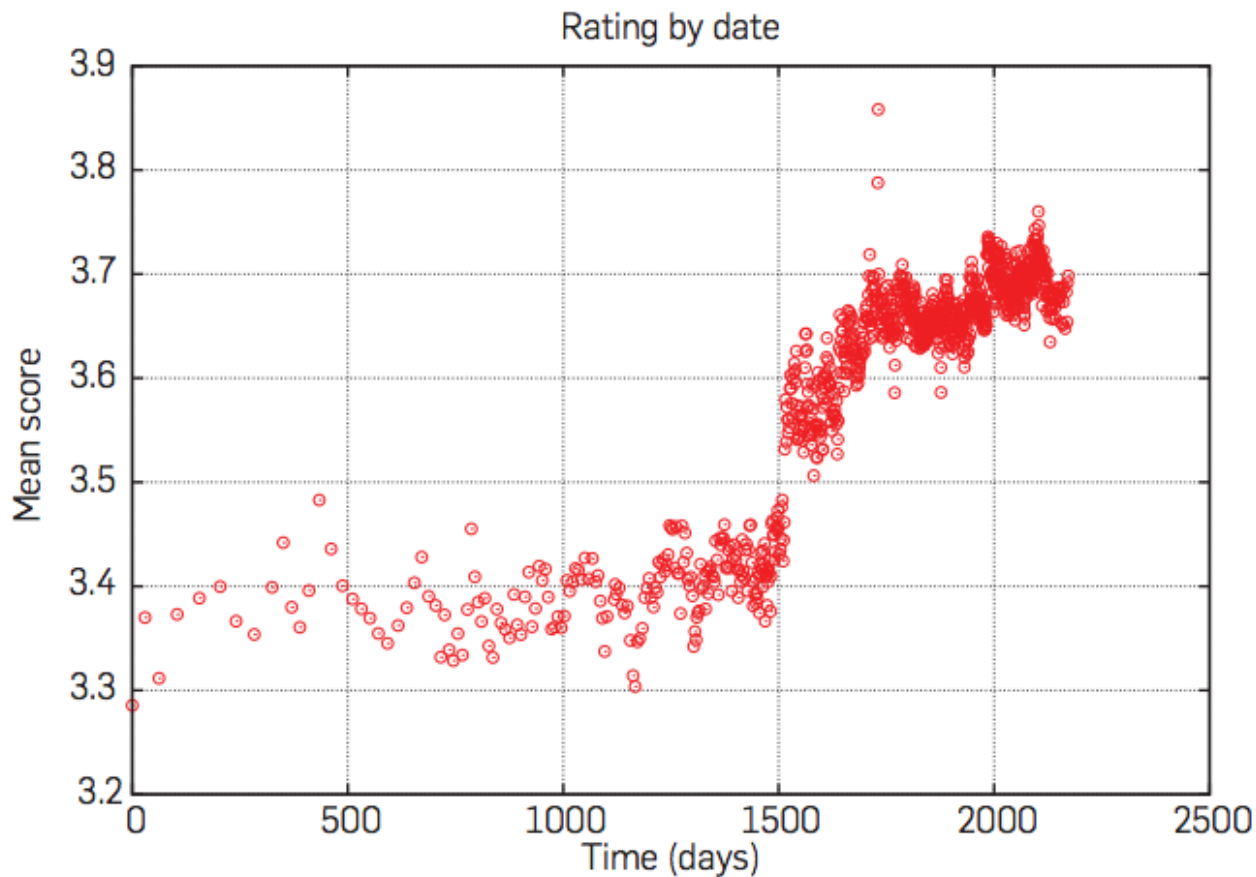
Data

- So far, collect observation pairs (x_i, y_i) for training
- Assume examples are independent and identically distributed (IID)

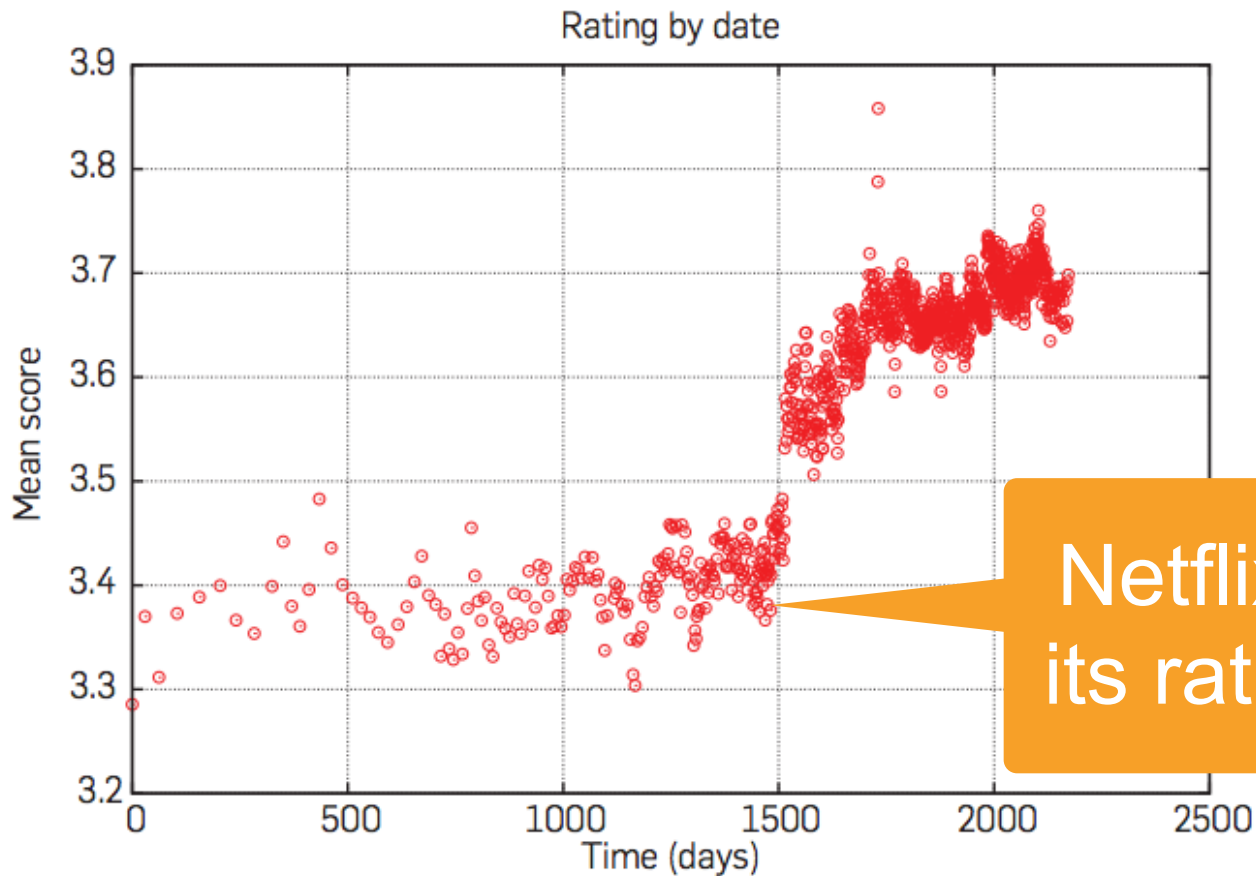
The order of the data does not matter



Time matters (Koren, 2009)

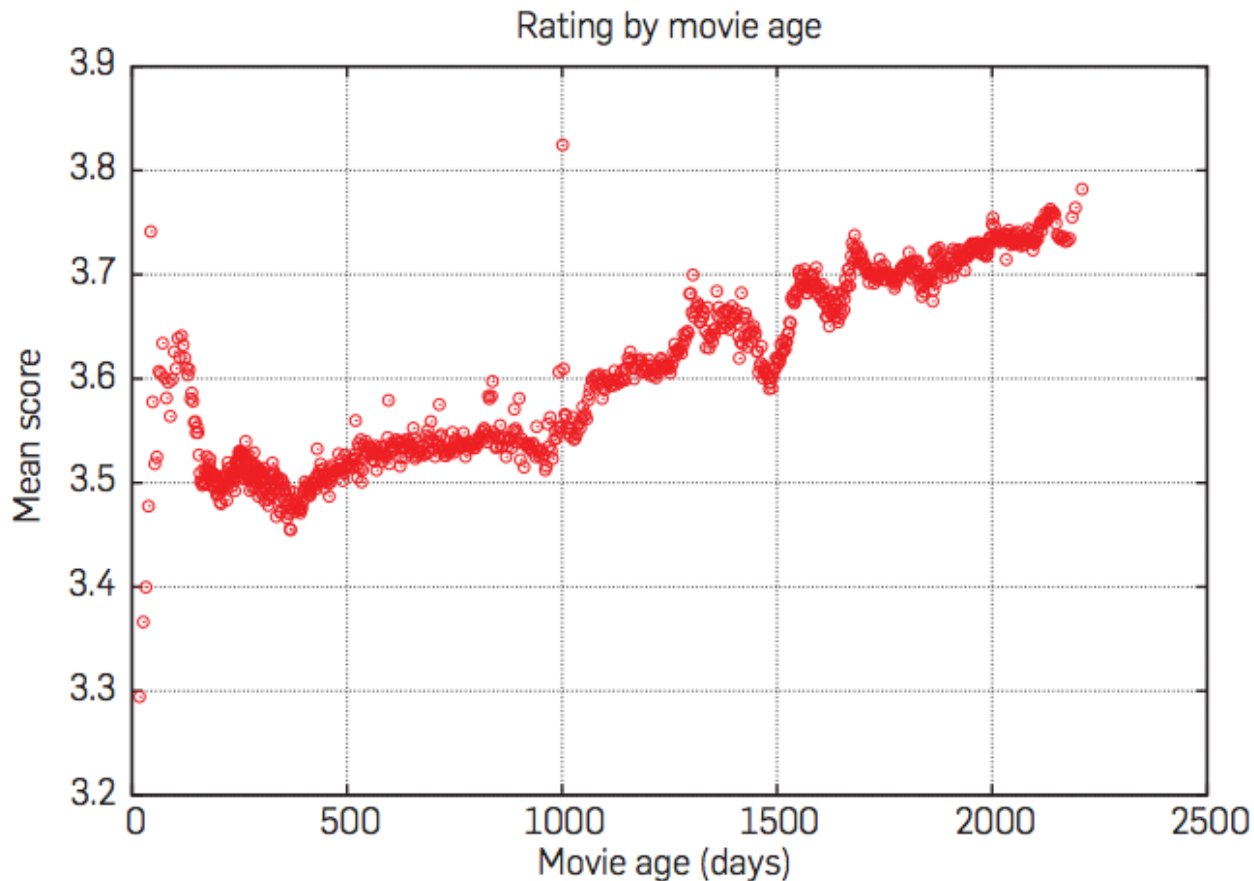


Time matters (Koren, 2009)

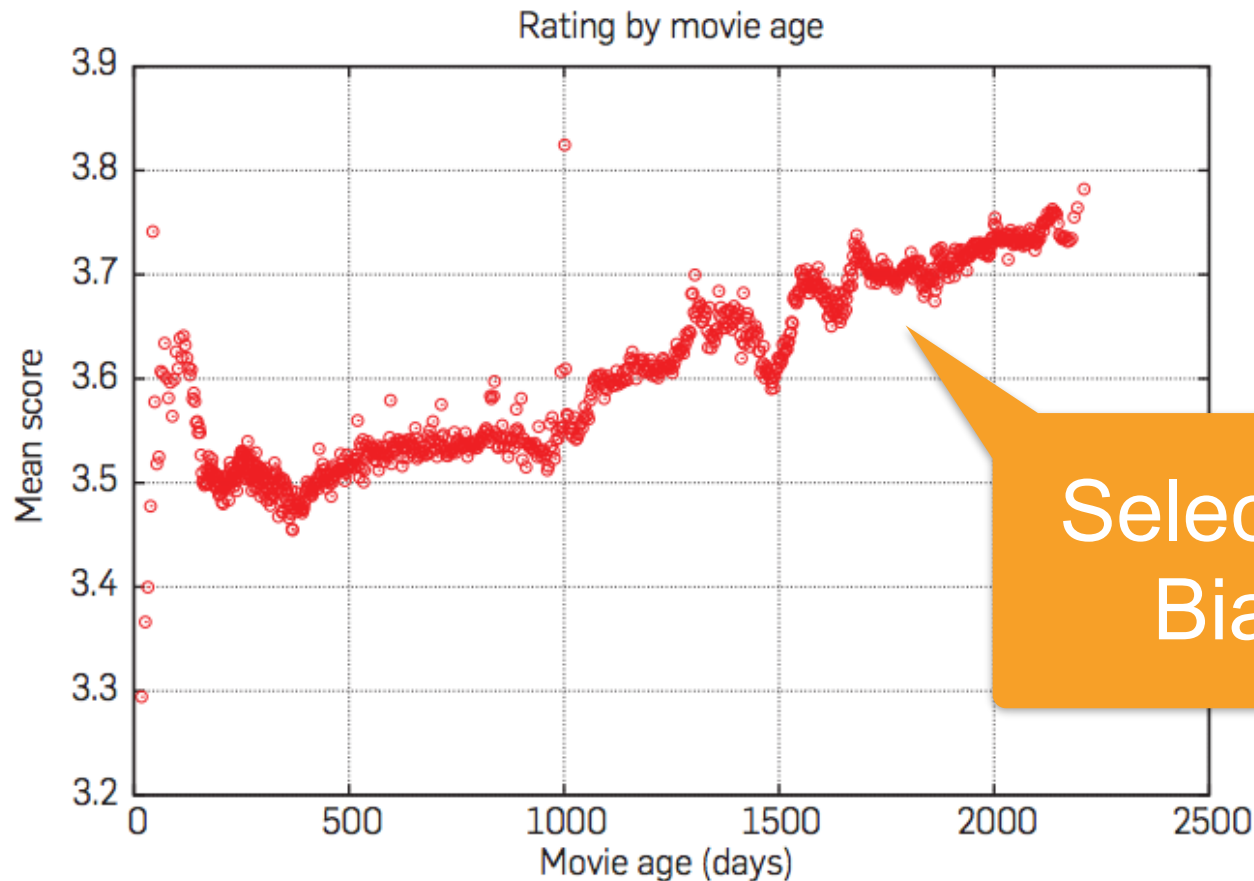


Netflix changed
its rating system

Time matters (Koren, 2009)



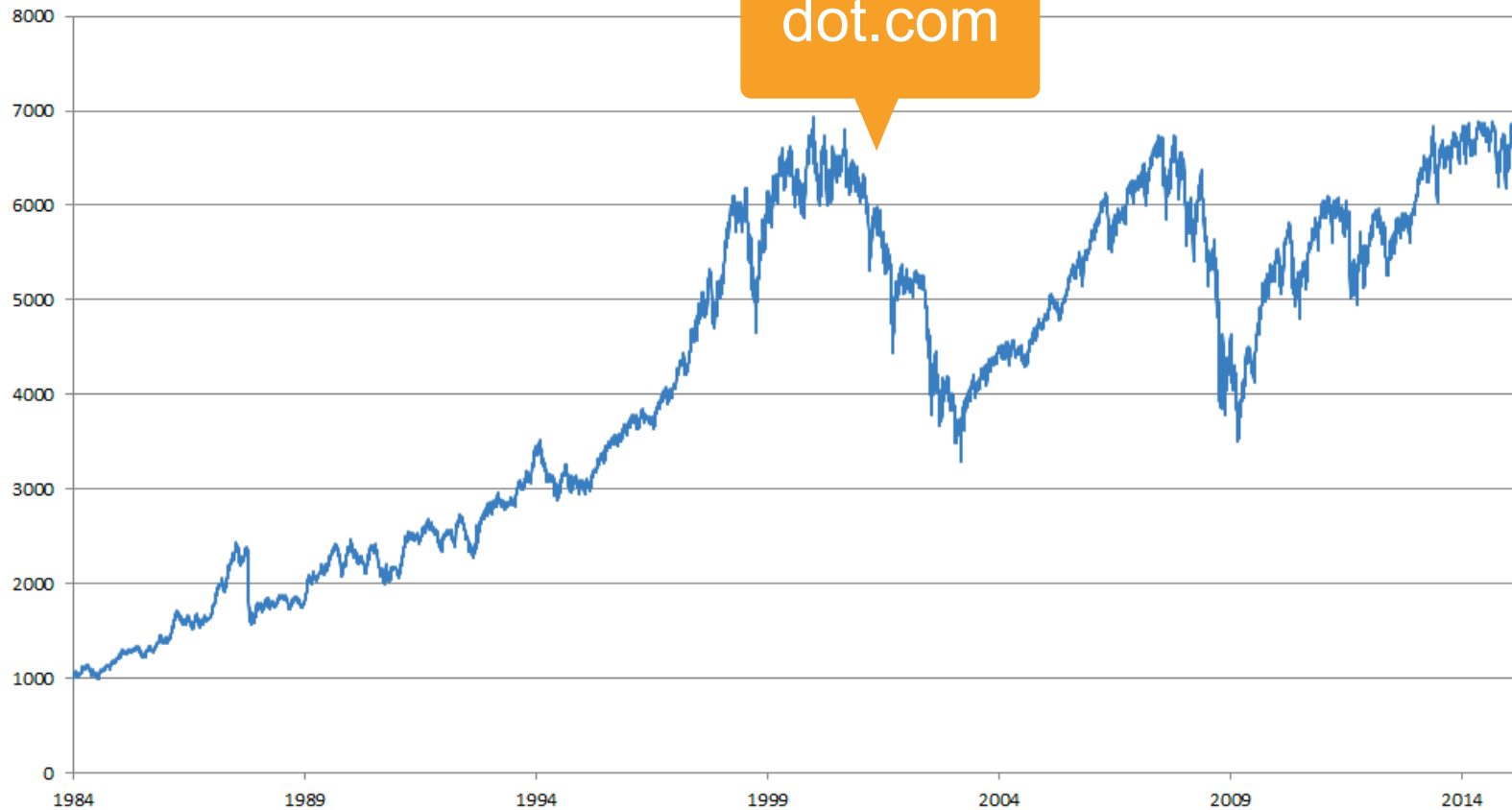
Time matters (Koren, 2009)



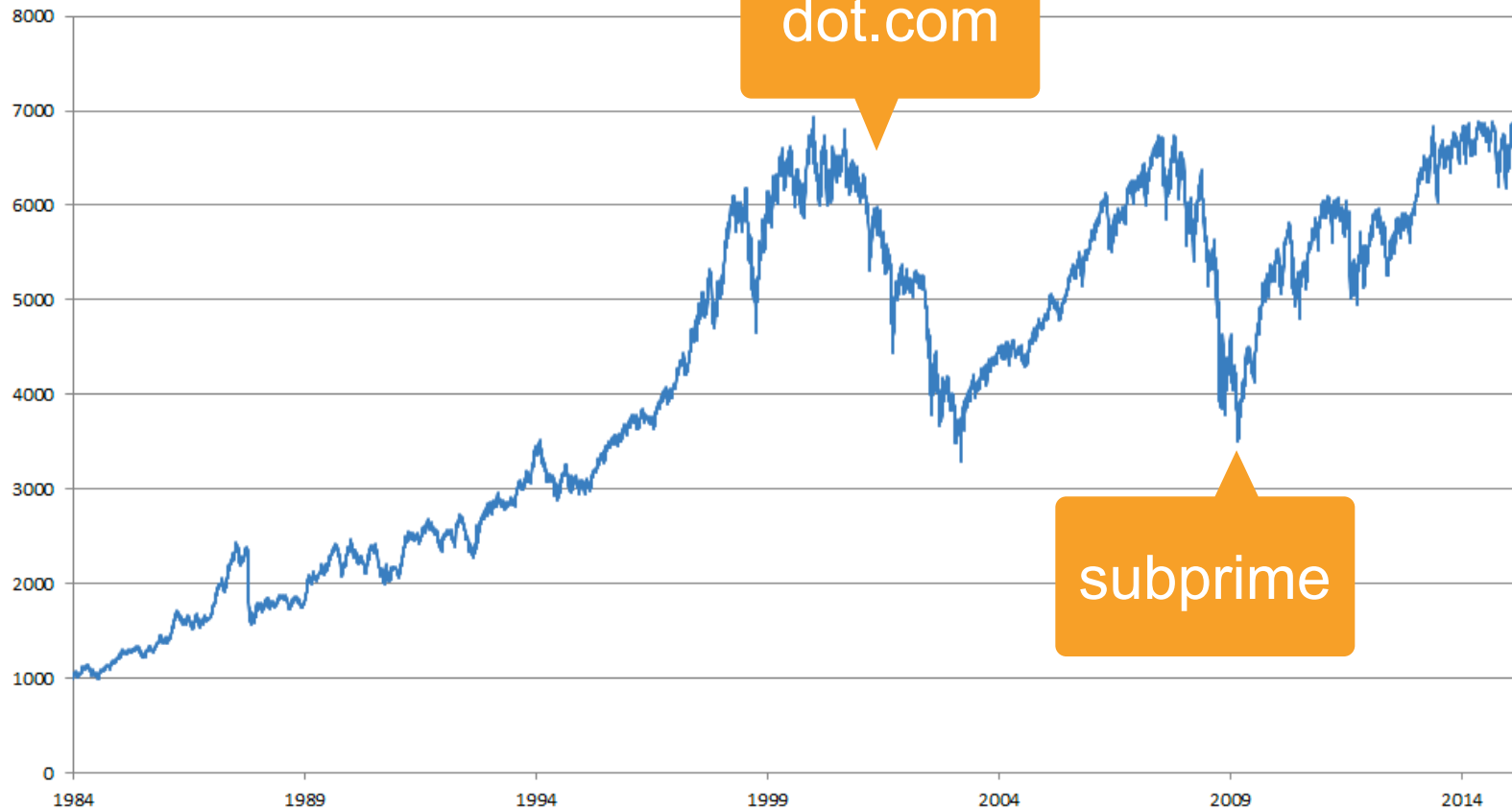
FTSE 100



FTSE 100



FTSE 100



Q2
earnings

rate cuts

rating
agencies

orange
hair tweets

TL;DR - Data usually isn't IID

inventory

Christmas

Black
Friday

prime day

back to
school

Language Models



Language Modeling

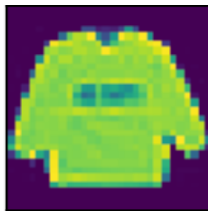
- Goal: predict the probability of a sentence, e.g.

$$p(\text{Deep, learning, is, fun, .})$$

- A fundamental task in Natural Language Processing
 - Typing - predict the next word
 - Machine translation - dog bites man vs man bites dog
 - Speech recognition
to recognize speech vs to wreck a nice beach

Text Preprocessing

- Sequence data has **long dependency** (very costly)
- Truncate into shorter fragments
- Transform examples into mini-batches with ndarrays



The Time Traveller (for so it will be)
was expounding a recondite matter to us;
twinkled, and his usually pale face was
fire burned brightly, and the soft radi-
lights in the lilies of silver caught
passed in our glasses. Our chairs, being
caressed us rather than submitted to be
luxurious after-dinner atmosphere when
free of the trammels of precision. And



(batch size, width, height, channel)



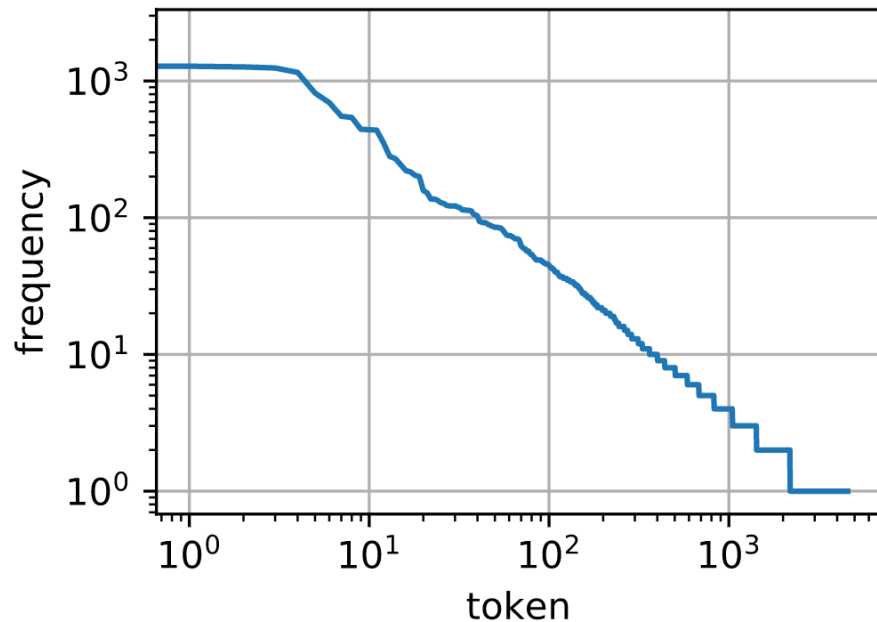
(batch size, sentence length)

Tokenization

- Basic Idea - map text into sequence of tokens
 - “Deep learning is fun” -> [“Deep”, “learning”, “is”, “fun”, “.”]
- **Character Encoding** (each character as a token)
 - Small vocabulary
 - Doesn't work so well (needs to learn spelling)
- **Word Encoding** (each word as a token)
 - Accurate spelling
 - Doesn't work so well (huge vocabulary = costly multinomial)
- **Byte Pair Encoding** (Goldilocks zone)
 - Frequent subsequences (like syllables)

Vocabulary

- Find unique tokens, map each one into a numerical index
 - “Deep” : 1, “learning” : 2, “is” : 3, “fun” : 4, “.” : 5
- The frequency of words often obeys a power law distribution
 - Map the tailing tokens, e.g. appears < 5 times, into a special “unknown” token



Minibatch Generation

The Time Machine by H. G. Wells

The	T	i	m	e	M	a	c	h	i	n	e		b	y		H	.	G	.	W	e	l	l	s
-----	---	---	---	---	---	---	---	---	---	---	---	--	---	---	--	---	---	---	---	---	---	---	---	---

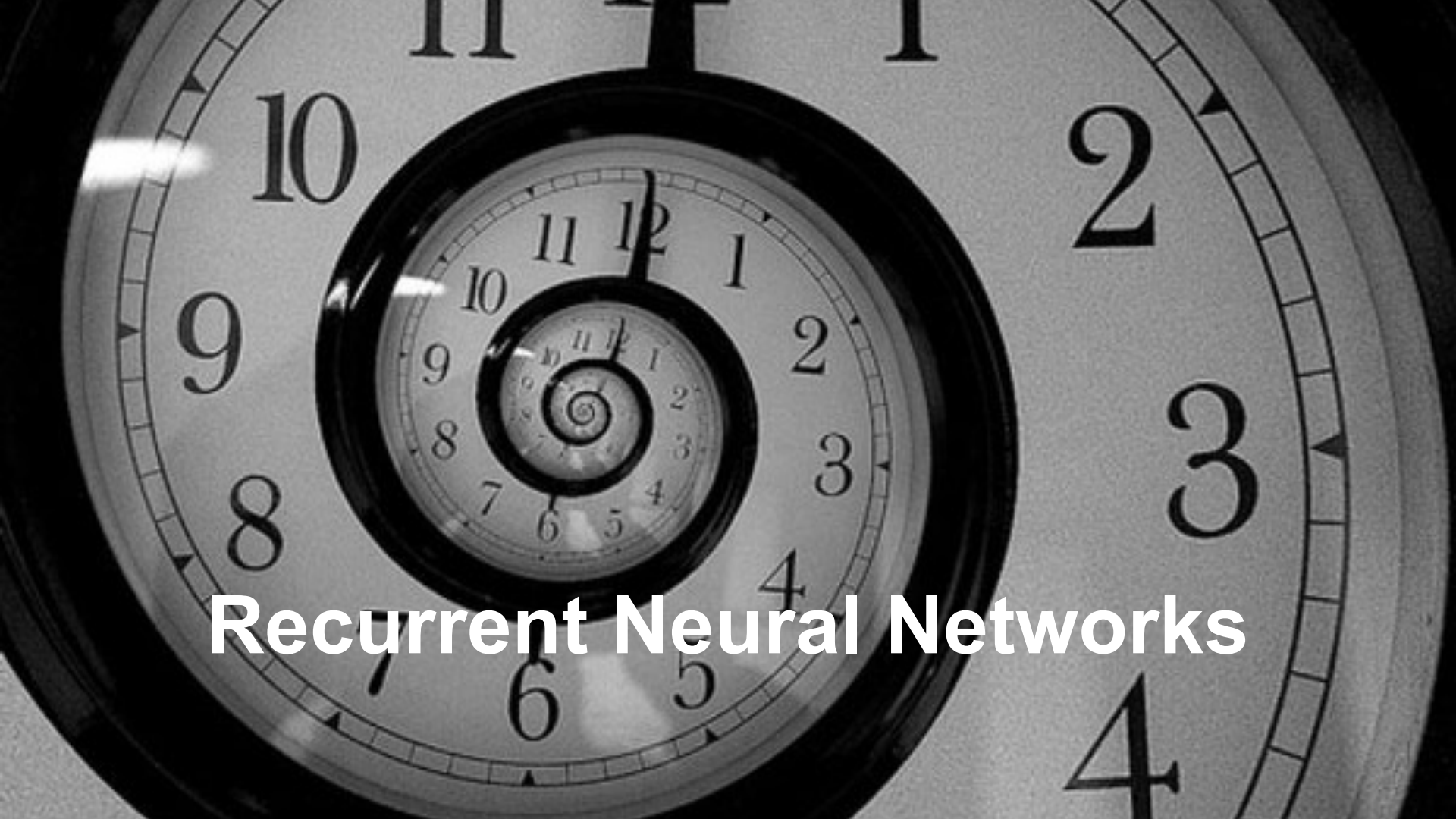
T	h	e		T	i	m	e	M	a	c	h	i	n	e		b	y		H	.	G	.	W	e	l	l	s
---	---	---	--	---	---	---	---	---	---	---	---	---	---	---	--	---	---	--	---	---	---	---	---	---	---	---	---

T	h	e		T	i	m	e	M	a	c	h	i	n	e		b	y		H	.	G	.	W	e	l	l	s
---	---	---	--	---	---	---	---	---	---	---	---	---	---	---	--	---	---	--	---	---	---	---	---	---	---	---	---

T	h	e		T	i	m	e	M	a	c	h	i	n	e		b	y		H	.	G	.	W	e	l	l	s
---	---	---	--	---	---	---	---	---	---	---	---	---	---	---	--	---	---	--	---	---	---	---	---	---	---	---	---

T	h	e		T	i	m	e	M	a	c	h	i	n	e		b	y		H	.	G	.	W	e	l	l	s
---	---	---	--	---	---	---	---	---	---	---	---	---	---	---	--	---	---	--	---	---	---	---	---	---	---	---	---

Text Preprocessing Notebook

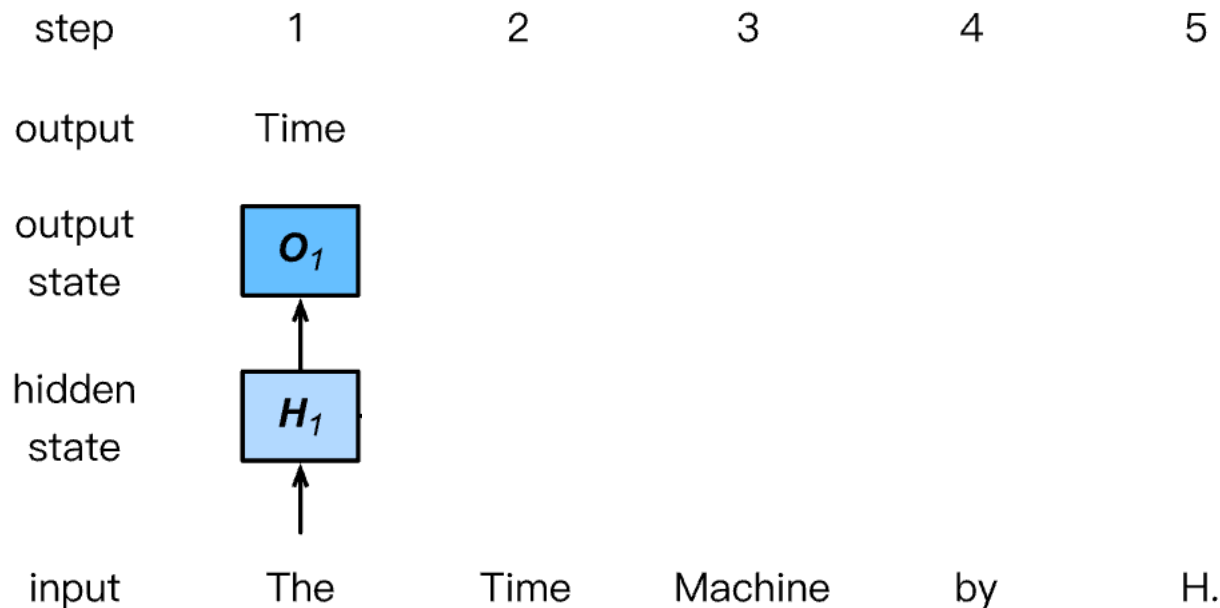


Recurrent Neural Networks

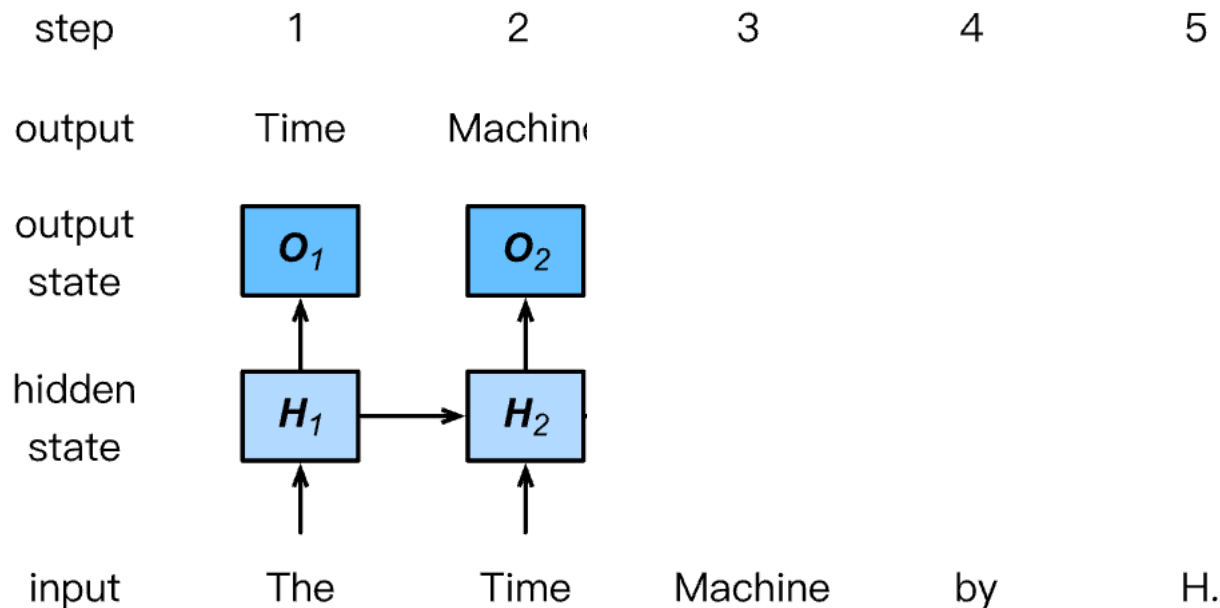
Steps in a Language Model

step	1	2	3	4	5
output					
output state					
hidden state					
input	The	Time	Machine	by	H.

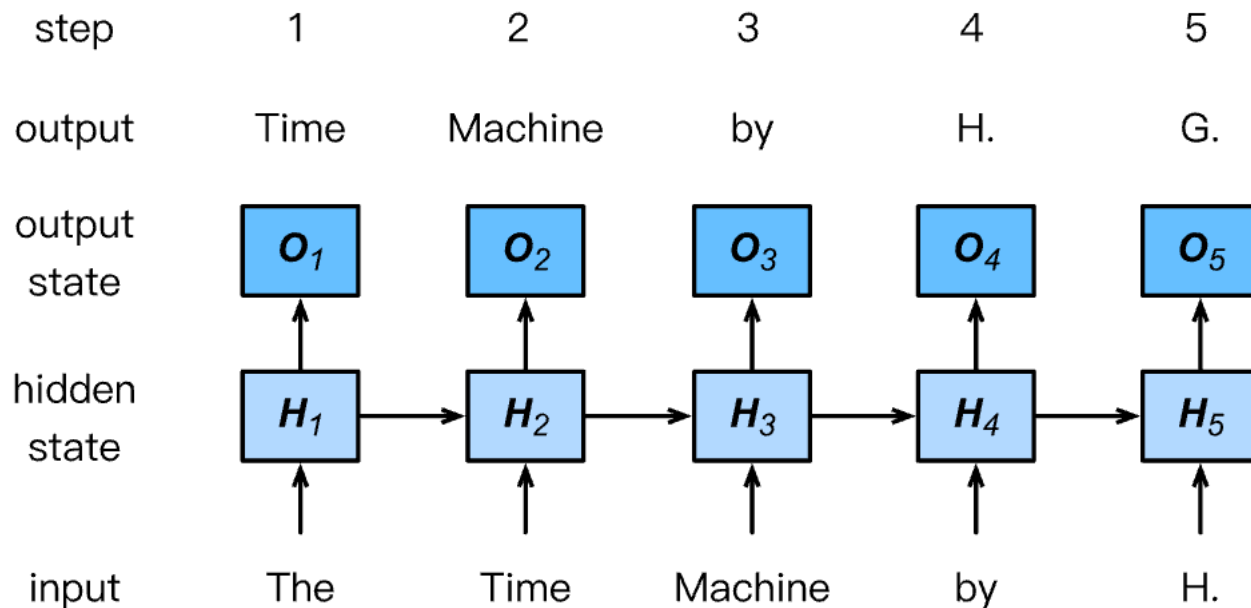
Steps in a Language Model



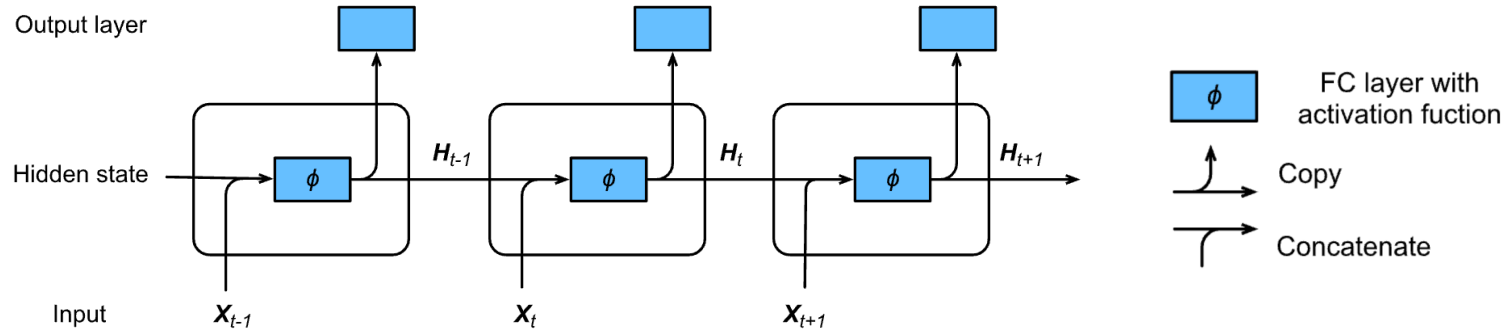
Steps in a Language Model



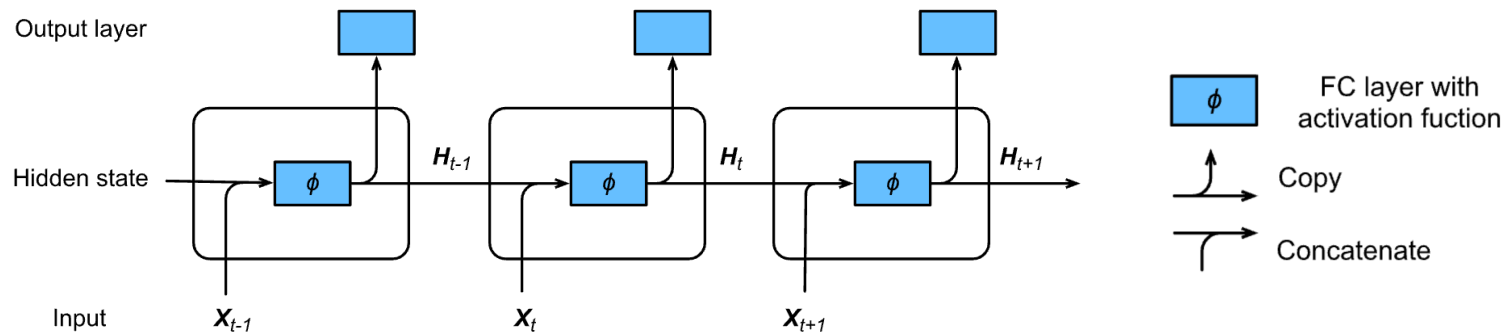
Steps in a Language Model



Recurrent Networks with Hidden States



Recurrent Networks with Hidden States



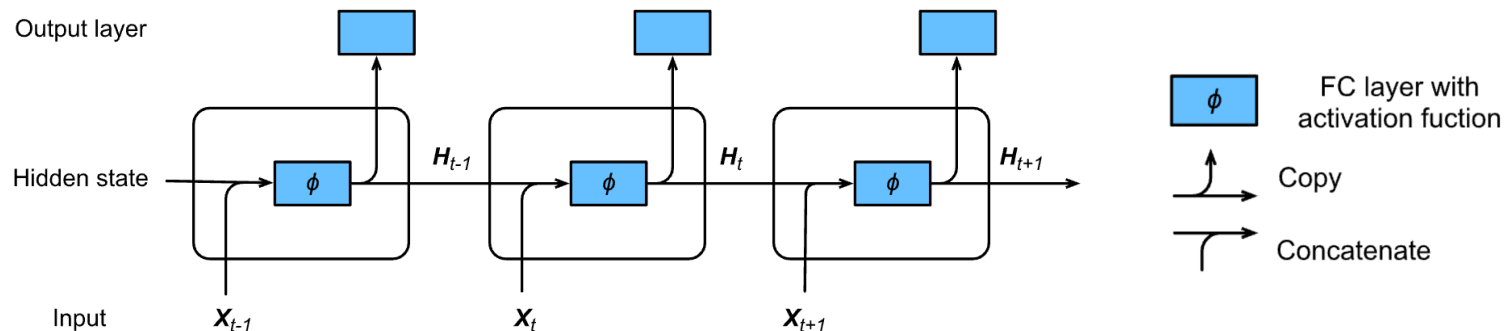
- Hidden State update

$$\mathbf{H}_t = \phi(\mathbf{W}_{hh}\mathbf{H}_{t-1} + \mathbf{W}_{hx}\mathbf{X}_{t-1} + \mathbf{b}_h)$$

- Observation update

$$\mathbf{o}_t = \mathbf{W}_{ho}\mathbf{H}_t + \mathbf{b}_o$$

Recurrent Networks with Hidden States



- Hidden State update

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- Observation update

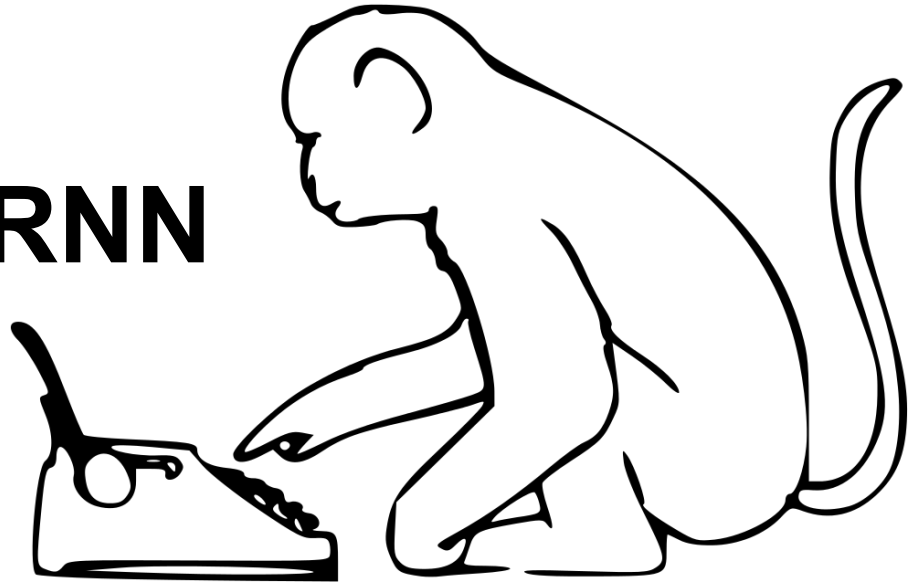
$$\mathbf{o}_t = \mathbf{W}_{ho}\mathbf{H}_t + \mathbf{b}_o$$

- Compare to MLP

$$\mathbf{H}_t = \phi(\mathbf{W}_{hx}\mathbf{X}_{t-1} + \mathbf{b}_h)$$

$$\mathbf{o}_t = \mathbf{W}_{ho}\mathbf{H}_t + \mathbf{b}_o$$

Implementing an RNN Language Model



Input Encoding

- Need to map input numerical indices to vectors
 - Pick granularity (words, characters, subwords)
 - Map to indicator vectors

```
npix.one_hot(np.array([0, 2]), len(vocab))
```

```
array([[1., 0., 0., 0., 0., 0., 0., 0., 0., 0.,  
       0., 0., 0., 0., 0., 0., 0., 0., 0., 0.,  
       0., 0., 1., 0., 0., 0., 0., 0., 0., 0.,  
       0., 0., 0., 0., 0., 0., 0., 0., 0., 0.]])
```

RNN with hidden state mechanics

- Input: vector sequence $\mathbf{x}_1, \dots, \mathbf{x}_T \in \mathbb{R}^d$
- Hidden states: $\mathbf{h}_1, \dots, \mathbf{h}_T \in \mathbb{R}^h$ where $\mathbf{h}_t = f(\mathbf{h}_{t-1}, \mathbf{x}_t)$
- Output: vector sequence $\mathbf{o}_1, \dots, \mathbf{o}_T \in \mathbb{R}^p$ where $\mathbf{o}_t = g(\mathbf{h}_t)$
 - p is the vocabulary size
 - $\mathbf{o}_{t,j}$ is confident score that the t -th token in the sequence equals to j -th token in the vocabulary
- Loss: measure the classification error on T tokens

Perplexity

- Typically measure accuracy with log-likelihood
 - This makes outputs of different length incomparable (e.g. bad model on short output has higher likelihood than excellent model on very long output)
 - Normalize log-likelihood to sequence length

$$-\sum_{t=1}^T \log p(y_t | \text{model}) \quad \text{vs.} \quad \pi := -\frac{1}{T} \sum_{t=1}^T \log p(y_t | \text{model})$$

- Perplexity is exponentiated version $\exp(\pi)$
(effectively number of possible choices on average)

Gradients

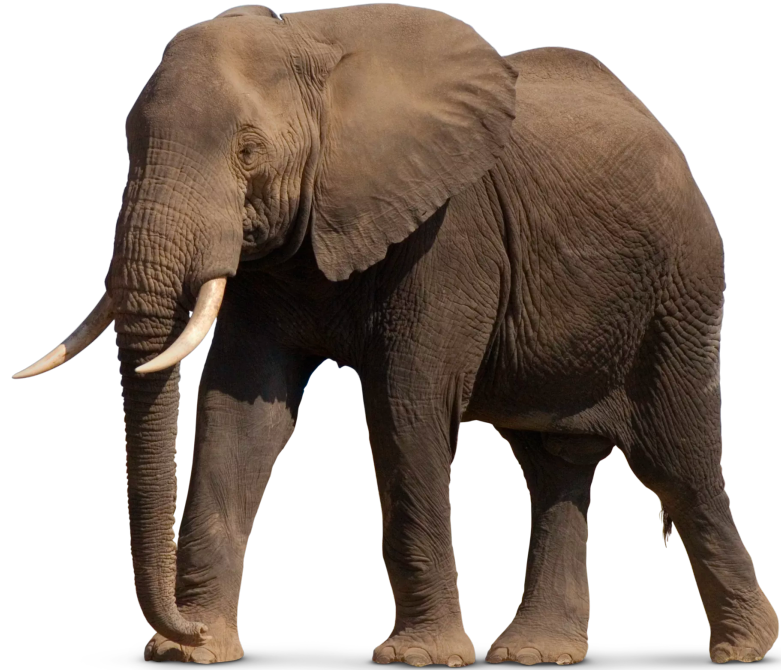
- Long chain of dependencies for backprop
 - Need to keep a lot of intermediate values in memory
 - Butterfly effect style dependencies
 - Gradients can vanish or diverge
- Clipping to prevent divergence

$$\mathbf{g} \leftarrow \min \left(1, \frac{\theta}{\|\mathbf{g}\|} \right) \mathbf{g}$$

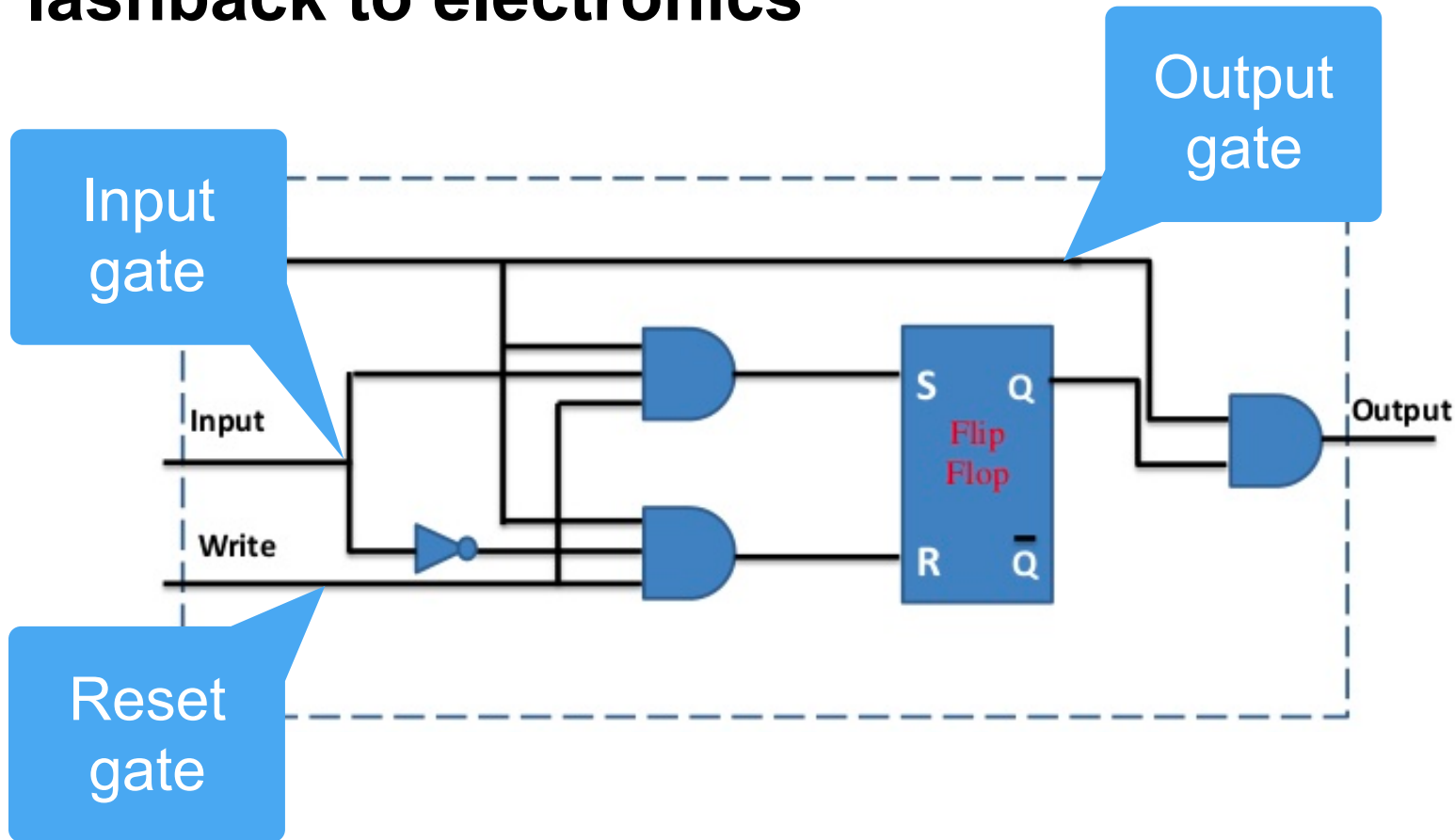
rescales to gradient of size at most θ

RNN Notebook

Long Short Term Memory



Flashback to electronics



Long Short Term Memory

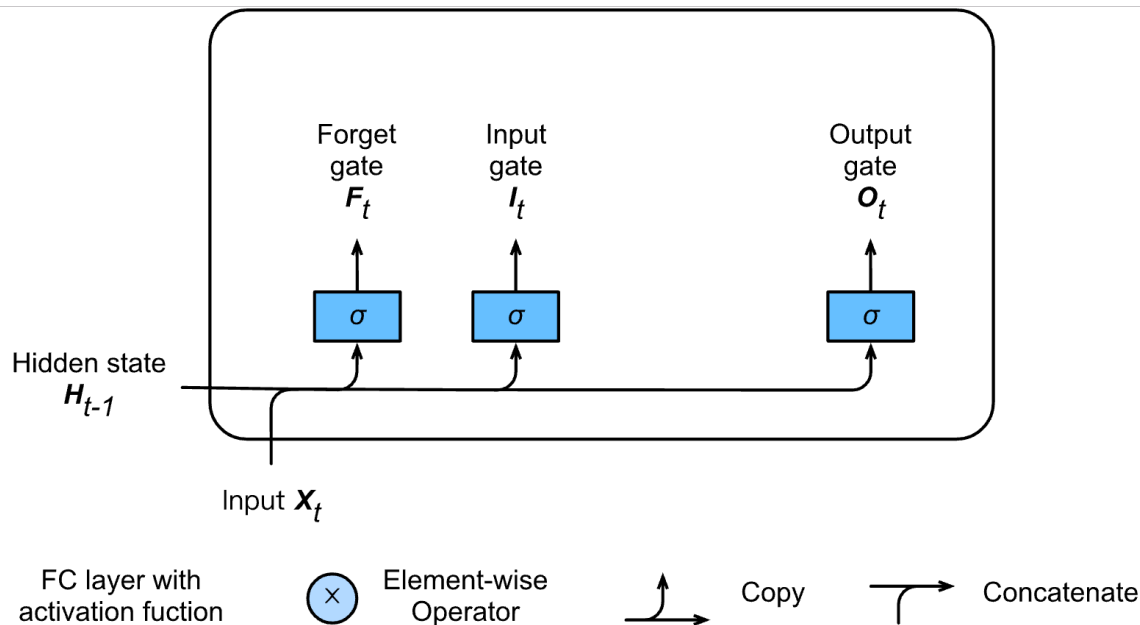
- **Forget gate**
Shrink values towards zero
- **Input gate**
Decide whether we should ignore the input data
- **Output gate**
Decide whether the hidden state is used for the output generated by the LSTM
- **Hidden state and Memory cell**

Gates

$$I_t = \sigma(X_t W_{xi} + H_{t-1} W_{hi} + b_i)$$

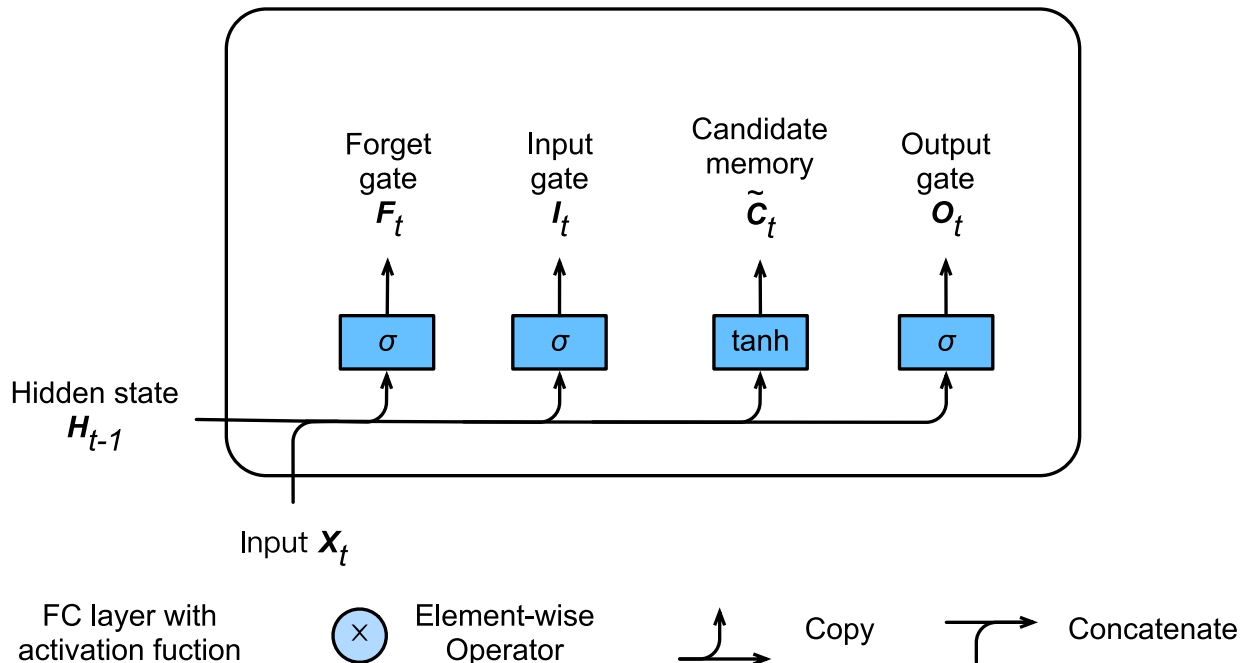
$$F_t = \sigma(X_t W_{xf} + H_{t-1} W_{hf} + b_f)$$

$$O_t = \sigma(X_t W_{xo} + H_{t-1} W_{ho} + b_o)$$



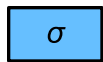
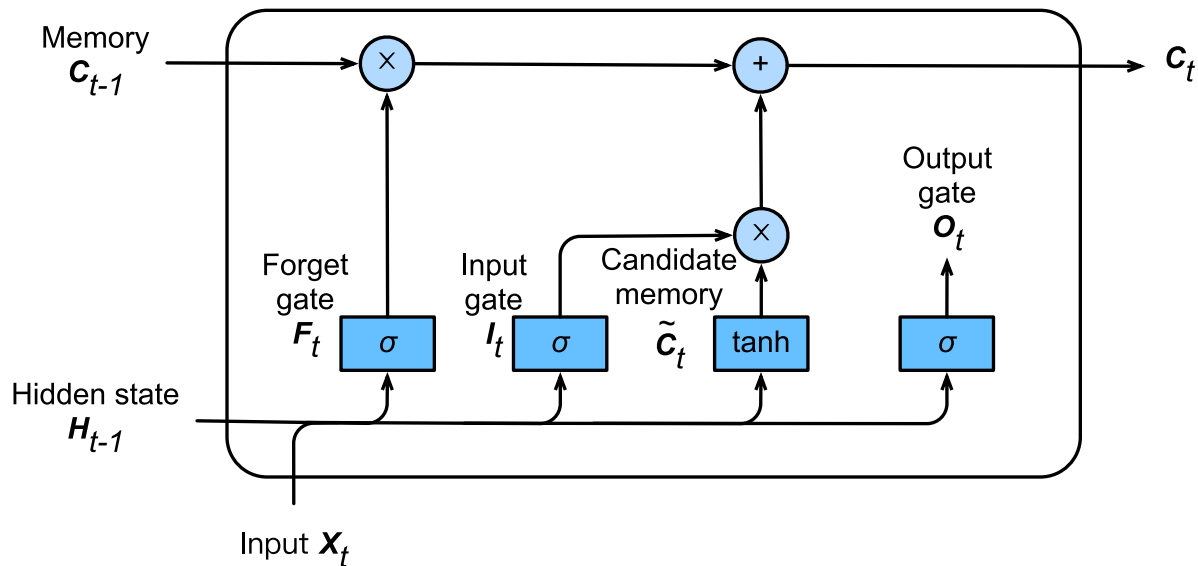
Candidate Memory Cell

$$\tilde{C}_t = \tanh(X_t W_{xc} + H_{t-1} W_{hc} + b_c)$$



Memory Cell

$$C_t = F_t \odot C_{t-1} + I_t \odot \tilde{C}_t$$



FC layer with
activation function



Element-wise
Operator



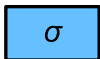
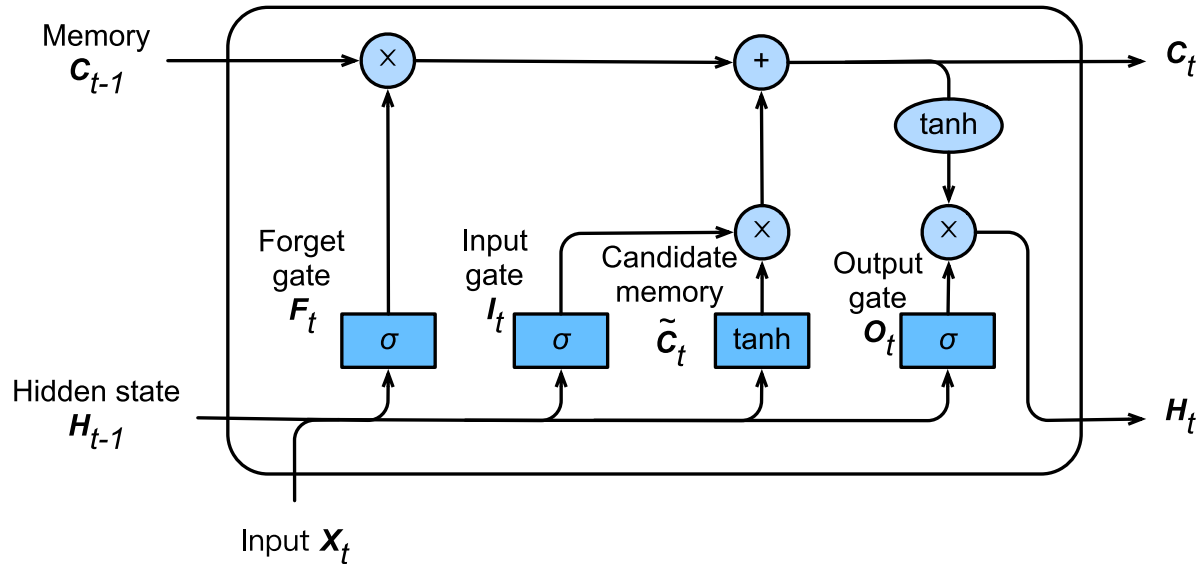
Copy



Concatenate

Hidden State / Output

$$H_t = O_t \odot \tanh(C_t)$$



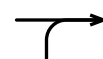
FC layer with
activation function



Element-wise
Operator

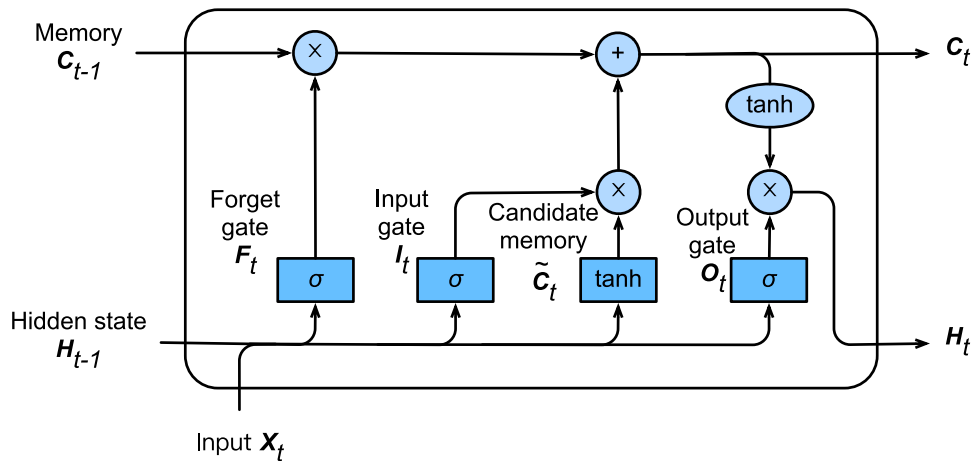


Copy



Concatenate

Hidden State / Output



$$I_t = \sigma(X_t W_{xi} + H_{t-1} W_{hi} + b_i)$$

$$F_t = \sigma(X_t W_{xf} + H_{t-1} W_{hf} + b_f)$$

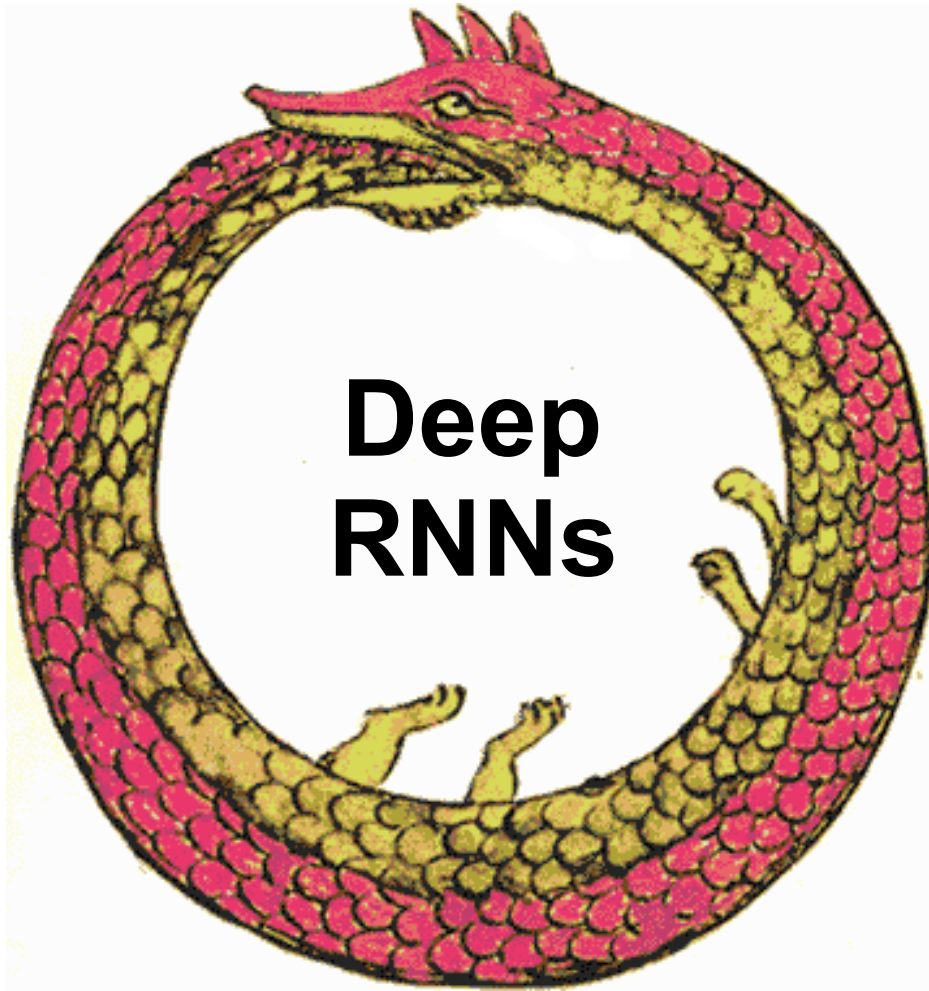
$$O_t = \sigma(X_t W_{xo} + H_{t-1} W_{ho} + b_o)$$

$$\tilde{C}_t = \tanh(X_t W_{xc} + H_{t-1} W_{hc} + b_c)$$

$$C_t = F_t \odot C_{t-1} + I_t \odot \tilde{C}_t$$

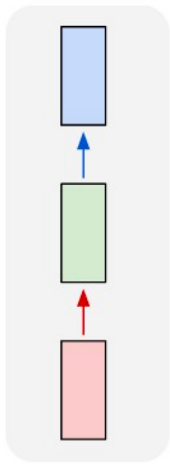
$$H_t = O_t \odot \tanh(C_t)$$

LSTM Notebook

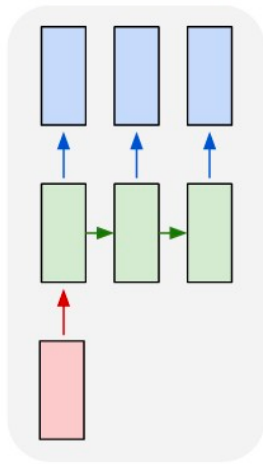


Using RNNs

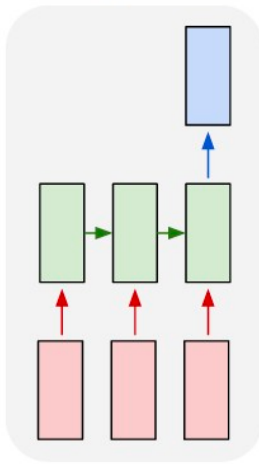
one to one



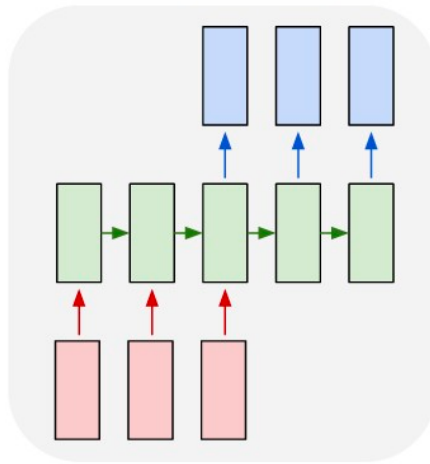
one to many



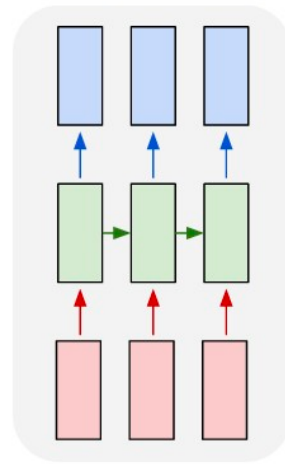
many to one



many to many



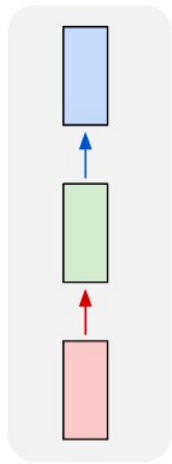
many to many



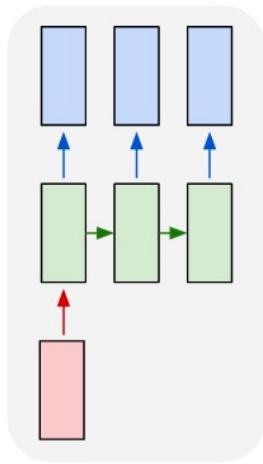
- Encode sequence
- Decode sequence
- Do both

Using RNNs

one to one

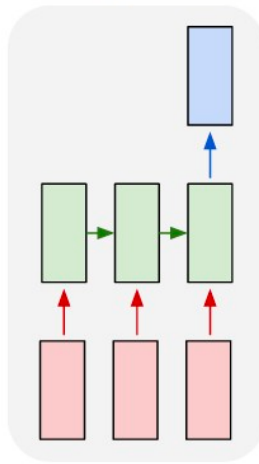


one to many



Poetry
Generation

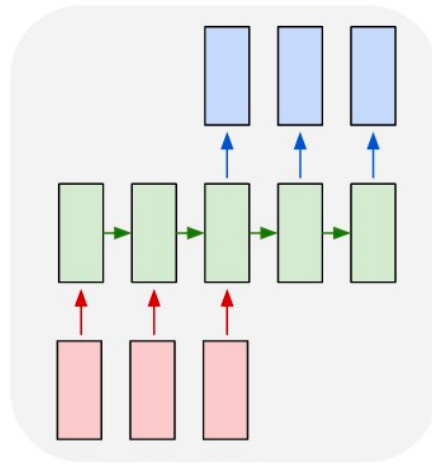
many to one



Sentiment
Analysis

Document
Classification

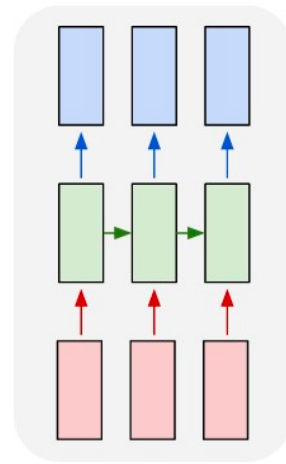
many to many



Question
Answering

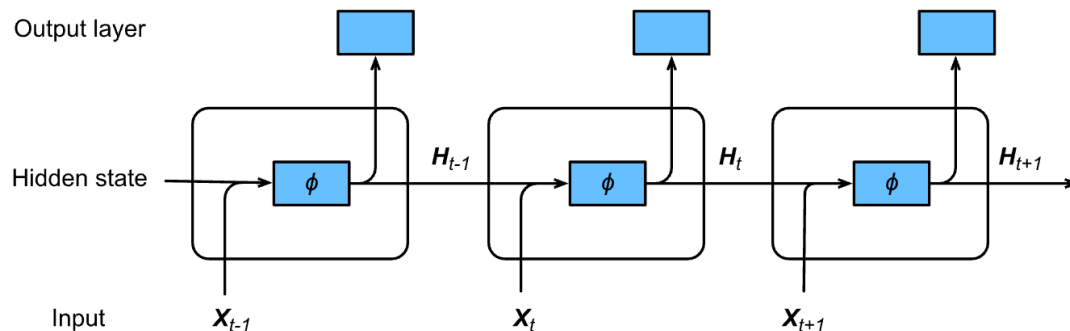
Machine
Translation

many to many



Named
Entity
Tagging

Recall - Recurrent Neural Networks



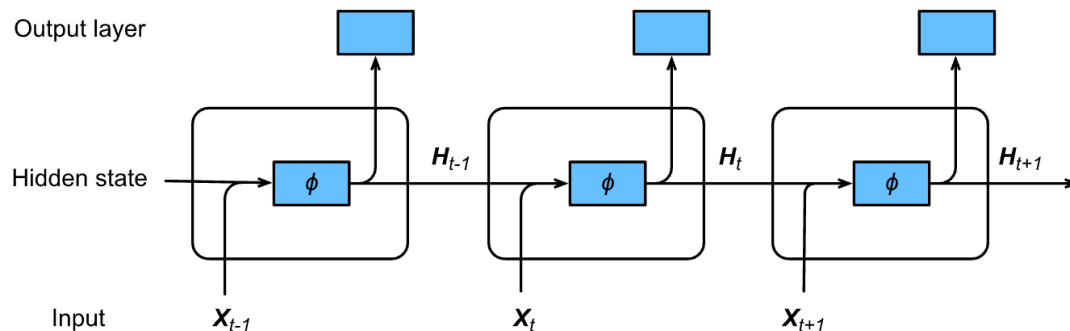
- Hidden State update

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Recall - Recurrent Neural Networks



- Hidden State update

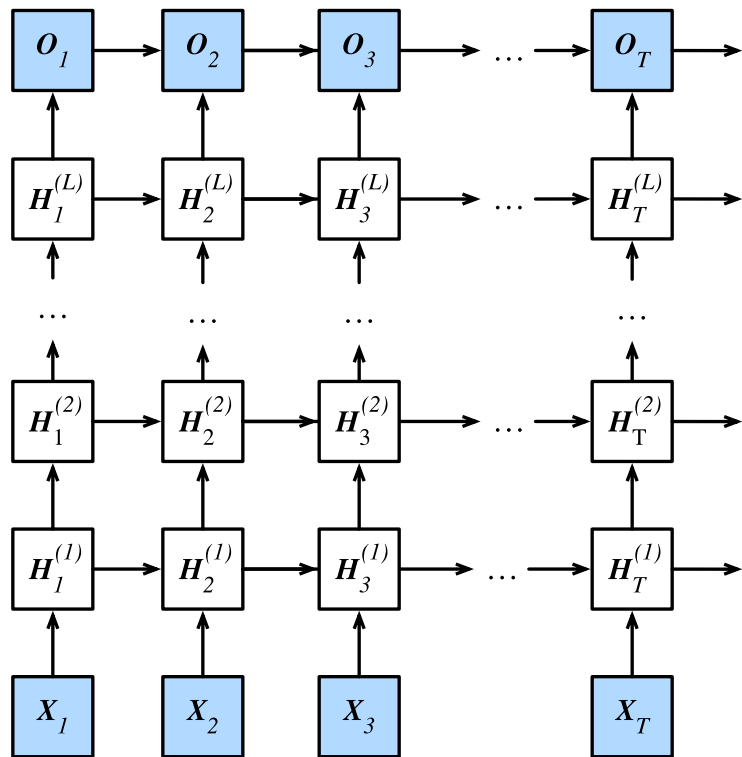
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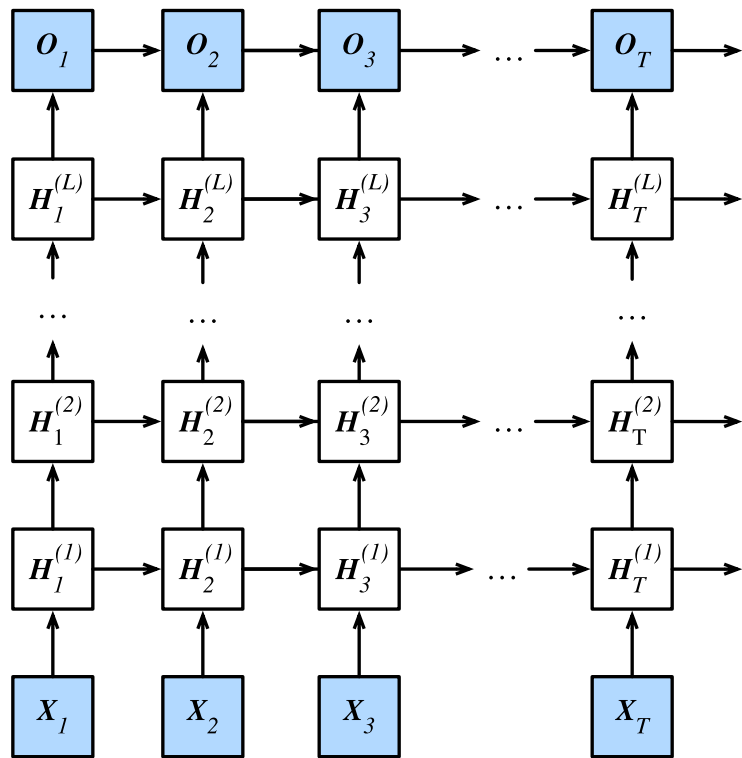
How to make
more nonlinear?

We go deeper per layer



- Shallow RNN
 - Input
 - Hidden layer
 - Output
- Deep RNN
 - Input
 - **Hidden layer**
 - **Hidden layer**
 - ...
 - Output

Plan B - We go deeper (multiple layers)



$$\mathbf{H}_t = f(\mathbf{H}_{t-1}, \mathbf{X}_t)$$

$$\mathbf{O}_t = g(\mathbf{H}_t)$$

$$\mathbf{H}_t^1 = f_1(\mathbf{H}_{t-1}^1, \mathbf{X}_t)$$

$$\mathbf{H}_t^j = f_j(\mathbf{H}_{t-1}^j, \mathbf{H}_t^{j-1})$$

$$\mathbf{O}_t = g(\mathbf{H}_t^L)$$



JOHN COLTRANE BOTH
DIRECTIONS AT ONCE
THE LOST ALBUM

Bidirectional RNNs

impulse!

impulse!

The Future Matters

```
I am _____  
I am _____ very hungry,  
I am _____ very hungry, I could eat half a pig.
```

The Future Matters

I am **happy**.

I am **not** very hungry,

I am **very** very hungry, I could eat half a pig.

The Future Matters

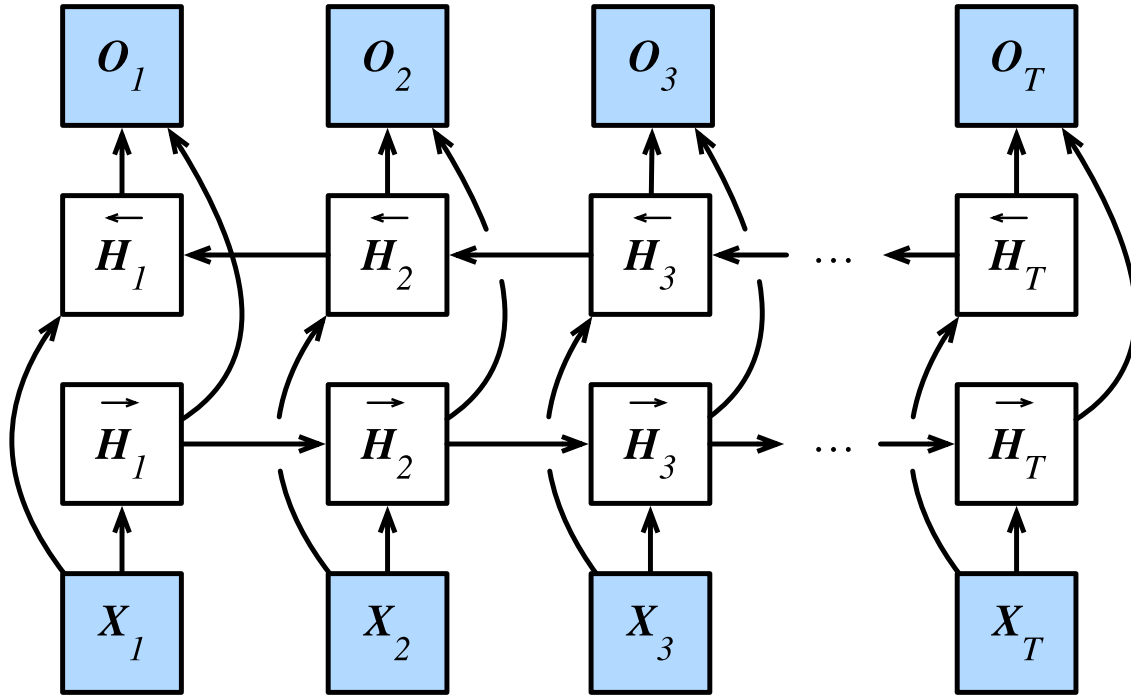
I am **happy**.

I am **not** very hungry,

I am **very** very hungry, I could eat half a pig.

- Very different words to fill in, depending on past and **future** context of a word.
- RNNs so far only look at the past
- In interpolation (fill in) we can use the future, too.

Bidirectional RNN



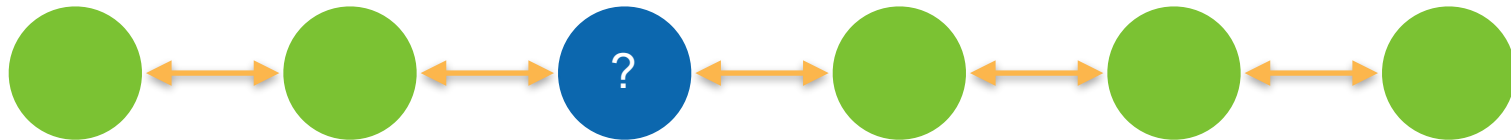
- One RNN forward
- Another one backward
- Combine both hidden states for output generation

```
Perplexity 1.2, 86219 tokens/sec on gpu(0)
time travellerererererererererererererererererererer
travellerererererererererererererererererererererer
```

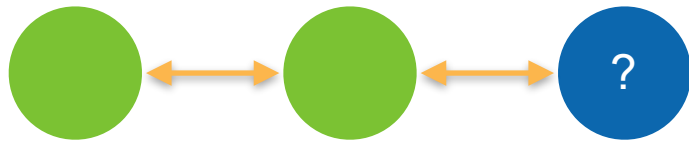
**This does not work for
sequence generation**

Reasons

- Training time



- Test time



Can still use it to **encode** the sequence

Summary

- RNN stores sequence information in hidden state
- GRU and LSTM use more sophisticated gates to handle long sequence information
- RNNs can go deeper and bi-directional

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- Covered today
- Partial covered today
- Not covered

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- Linear algebra
- Prob & statistics
- Gradient

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Basic models

- Linear regression
- Image classification
- Softmax regression
- Multilayer perceptron

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Machine learning

- Loss function
- Regularization
- Model selection
- Environment

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Basic models

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- Softmax regression
- Multilayer perceptron

CNNs

- Convolution, LeNet
- Alex, VGG, Inception, ResNet

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Basic models

- Linear regression
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- Softmax regression
- Multilayer perceptron

Performance

- Numerical stability
- multi-GPU Training

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- Convolution, LeNet
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- Transformer
- BERT

<http://courses.d2l.ai/odsc2019/>

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- Momentum, RMSProp, Adam

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Next steps

- Textbook: numpy.d2l.ai
- Toolkit for computer vision: gluon-cv.mxnet.io
- Toolkit for natural language processing: gluon-nlp.mxnet.io
- Toolkit for time series: gluon-ts.mxnet.io
- Toolkit for graph neural networks: dgl.ai
- Deep learning compiler: tvm.ai