

Dive into Deep Learning in 1 Day

1 Basics · 2 Convnets · 3 Computation · 4 Sequences

ODSC 2019

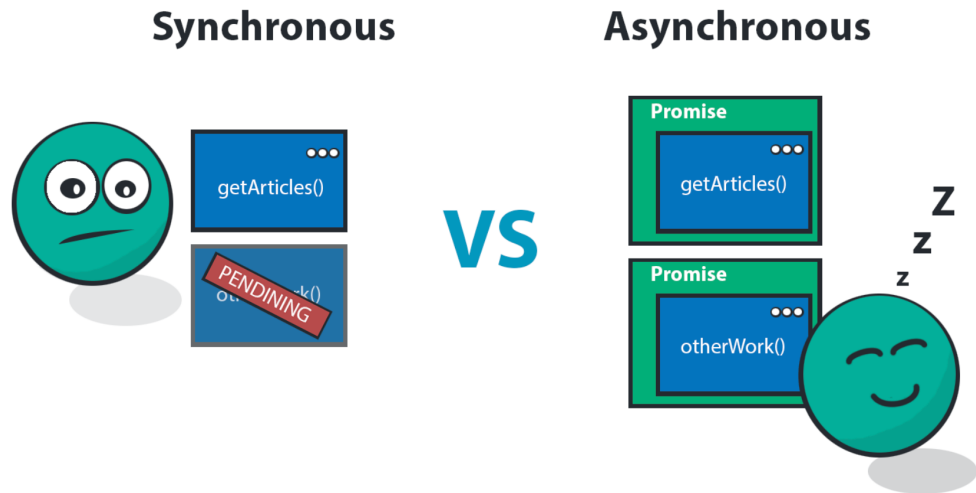
Alex Smola

<http://courses.d2l.ai/odsc2019/>

Outline

- Performance
 - Async-computation
 - Multi-GPU/machine training
- Computer Vision
 - Image augmentation
 - Fine tuning

Asynchronous Computing & Parallelization



Asynchronous Execution

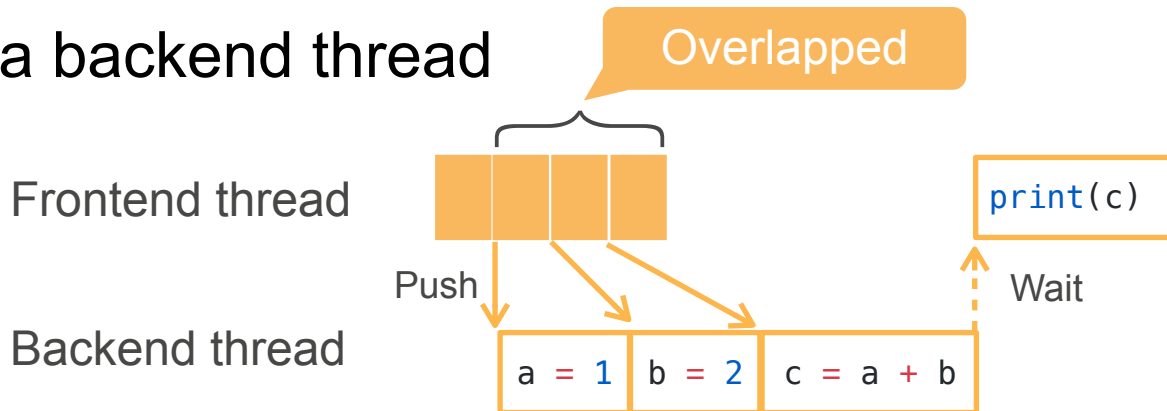
- Execute one-by-one



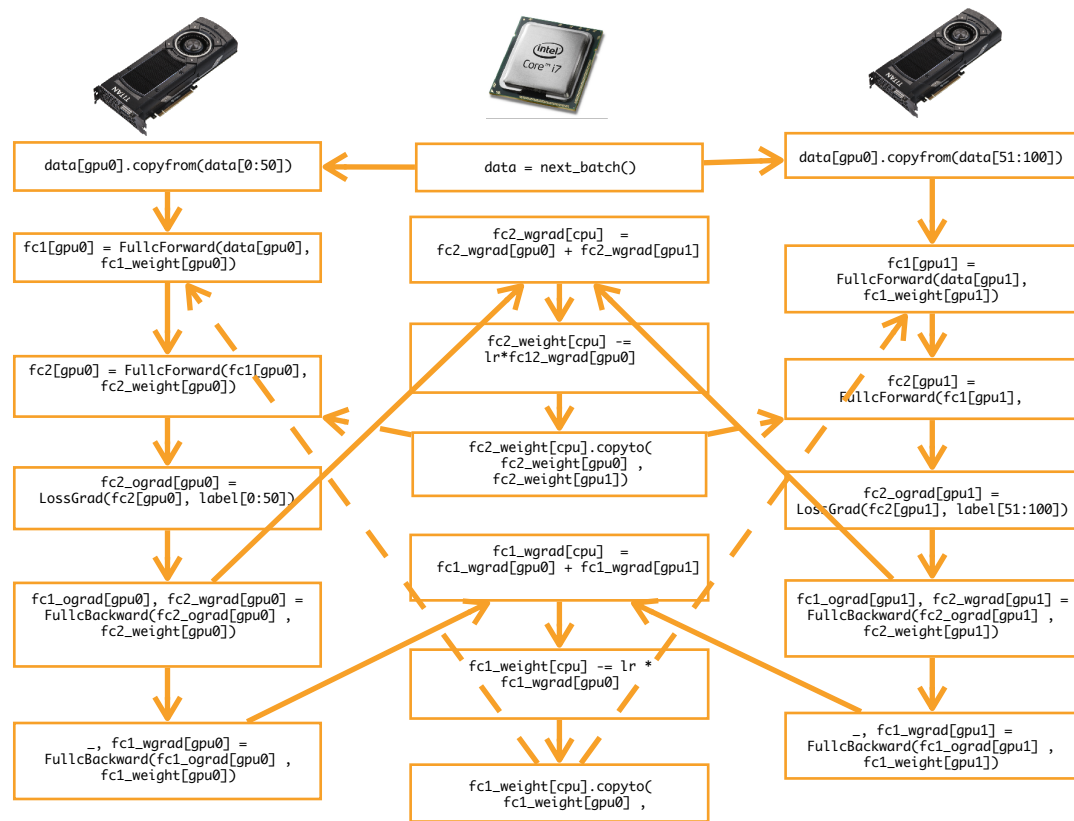
System overhead

```
a = 1
b = 2
c = a + b
print(c)
```

- With a backend thread



Writing Parallel Program is Painful



Single hidden-layer
MLP with 2 GPUs

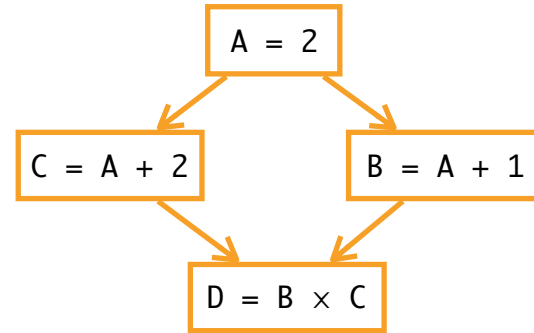
Scales to hundreds
of layers and tens
of GPUs

Auto Parallelization

Write serial programs

```
A = nd.ones((2,2)) * 2  
C = A + 2  
B = A + 1  
D = B * C
```

Run in parallel



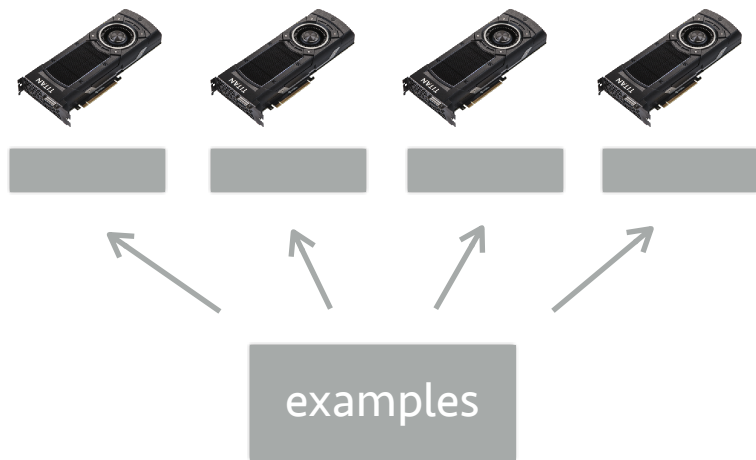
Data Parallelism



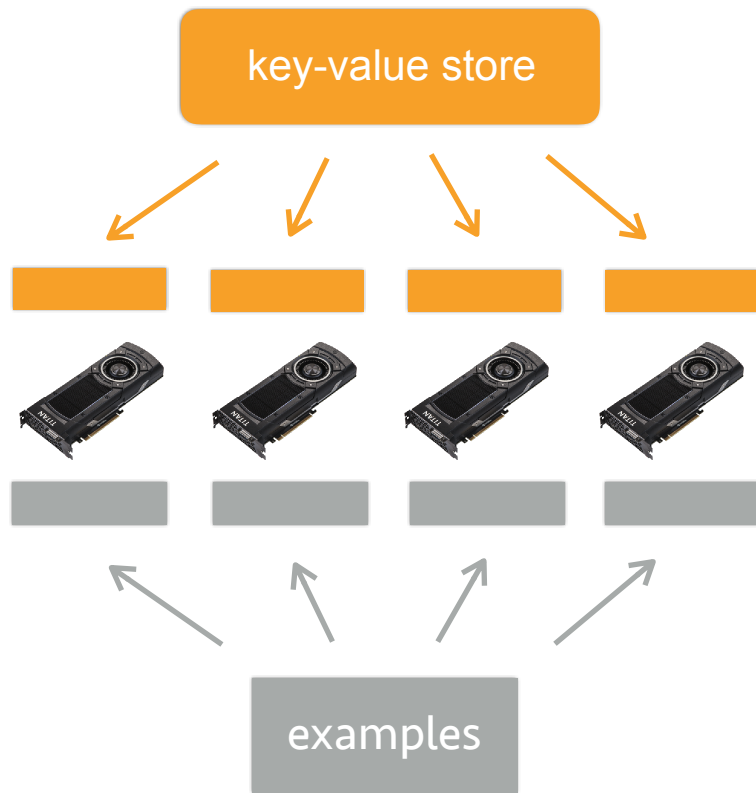
examples

Data Parallelism

1. Read a data partition

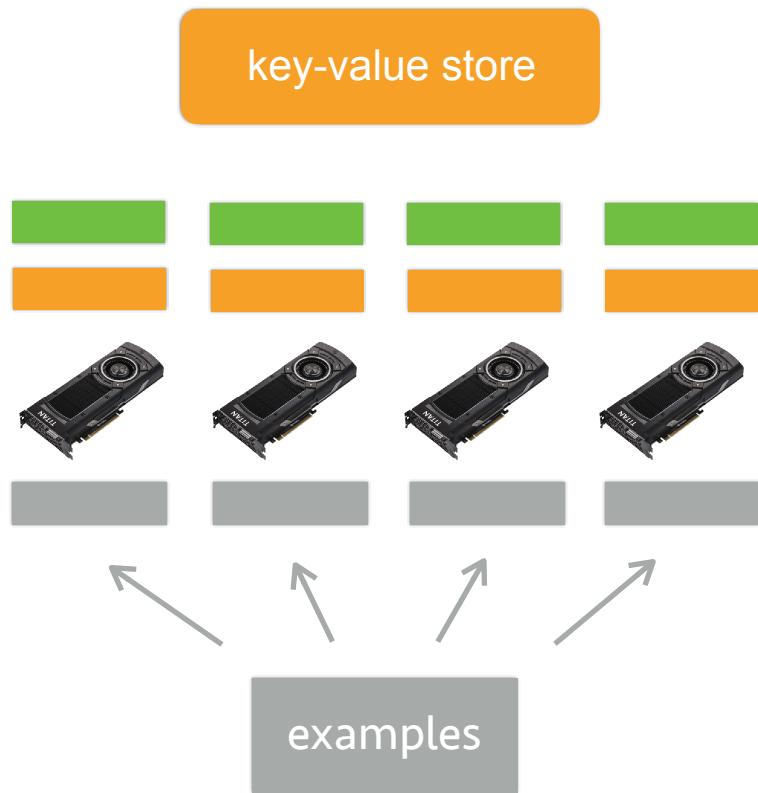


Data Parallelism



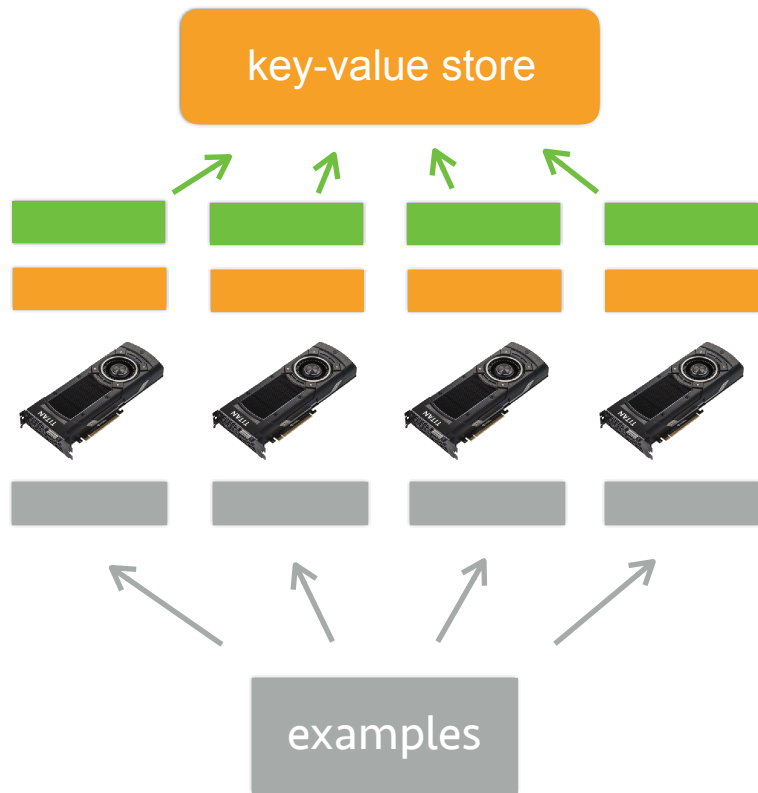
1. Read a data partition
2. Pull the parameters

Data Parallelism



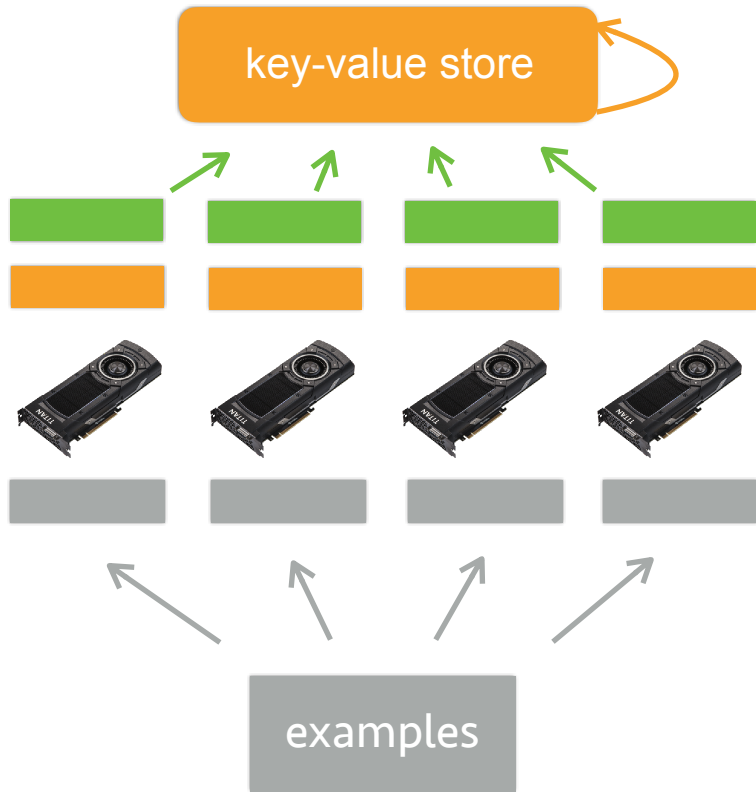
1. Read a data partition
2. Pull the parameters
3. Compute the gradient

Data Parallelism



1. Read a data partition
2. Pull the parameters
3. Compute the gradient
4. Push the gradient

Data Parallelism



1. Read a data partition
2. Pull the parameters
3. Compute the gradient
4. Push the gradient
5. Update the parameters

Distributed Training



Distributed Computing

key-value store



examples

Distributed Computing

key-value store



examples

Store data in
a distributed filesystem

Distributed Computing

key-value store



multiple
worker machines



Store data in
a distributed filesystem

Distributed Computing



multiple
server machines



multiple
worker machines



Store data in
a distributed filesystem

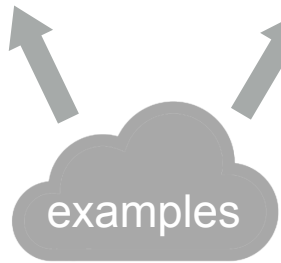
Distributed Computing



multiple
server machines



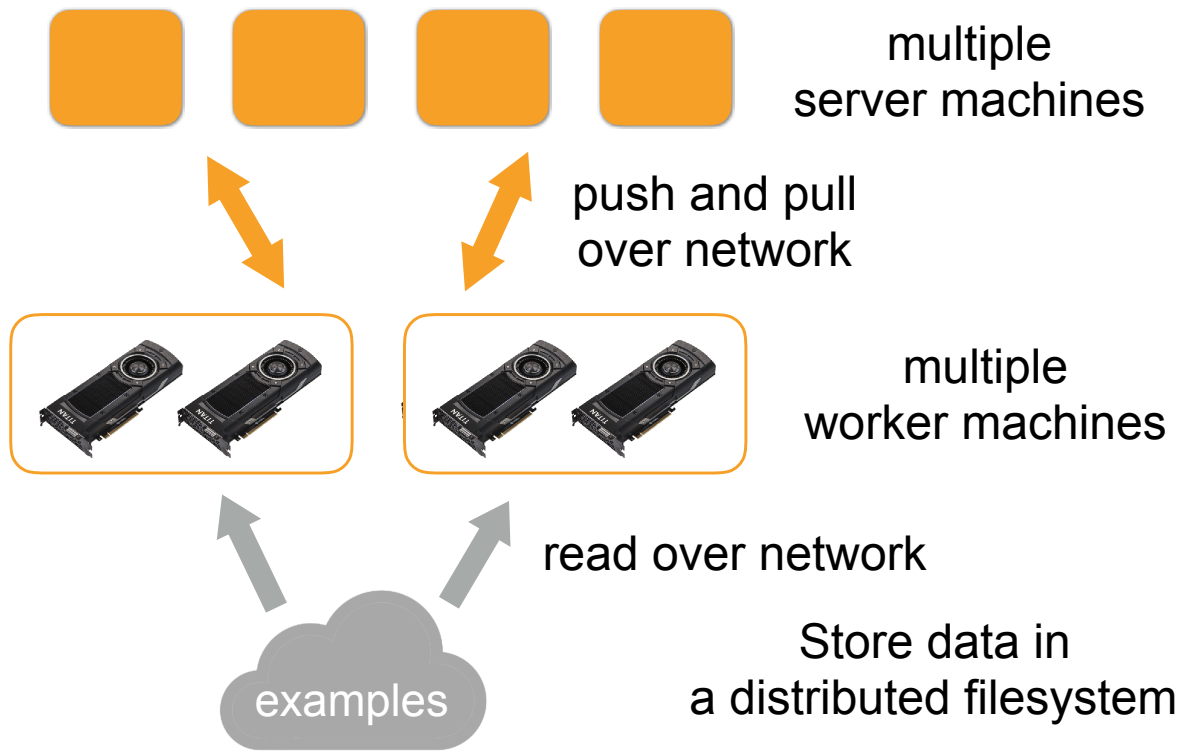
multiple
worker machines



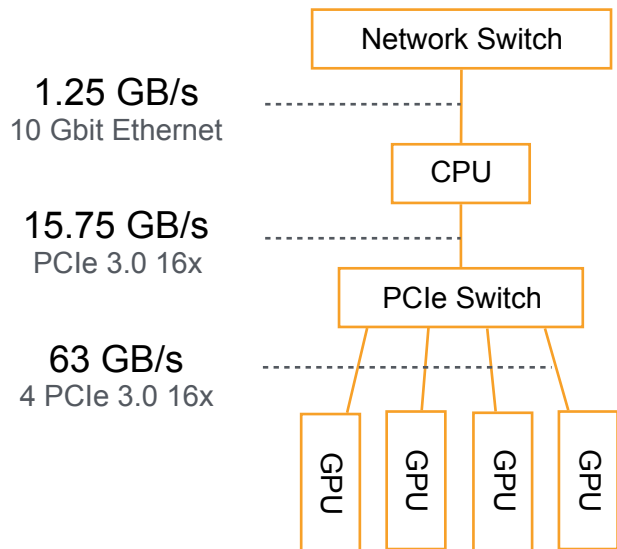
read over network

Store data in
a distributed filesystem

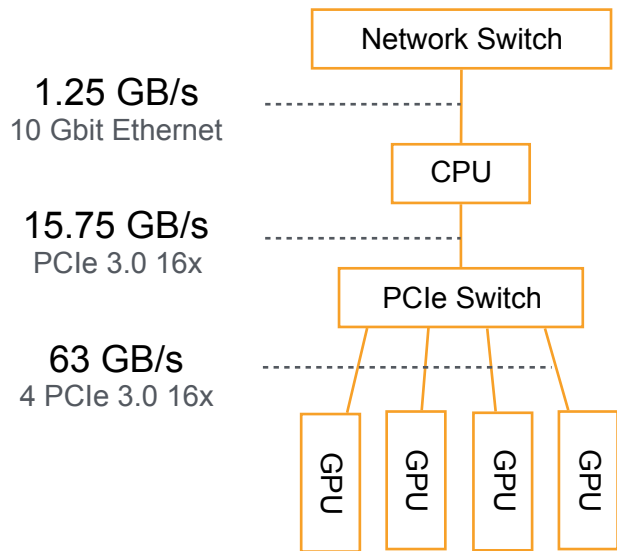
Distributed Computing



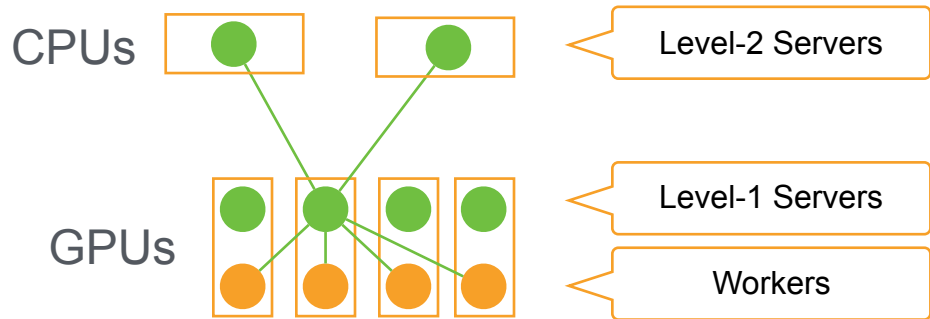
GPU Machine Hierarchy



GPU Machine Hierarchy

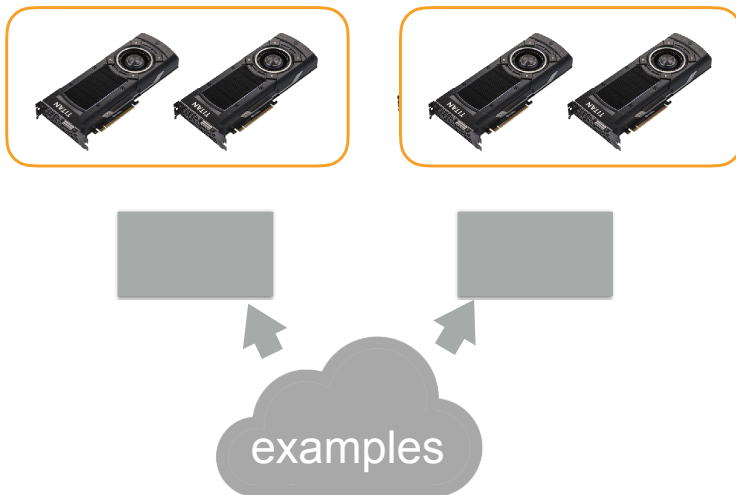


Hierarchical parameter server



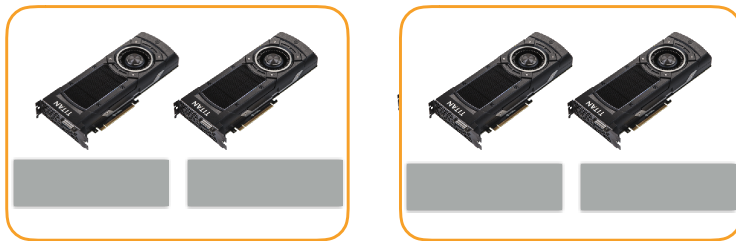
Iterating a Batch

- Each worker machine read a part of the data batch

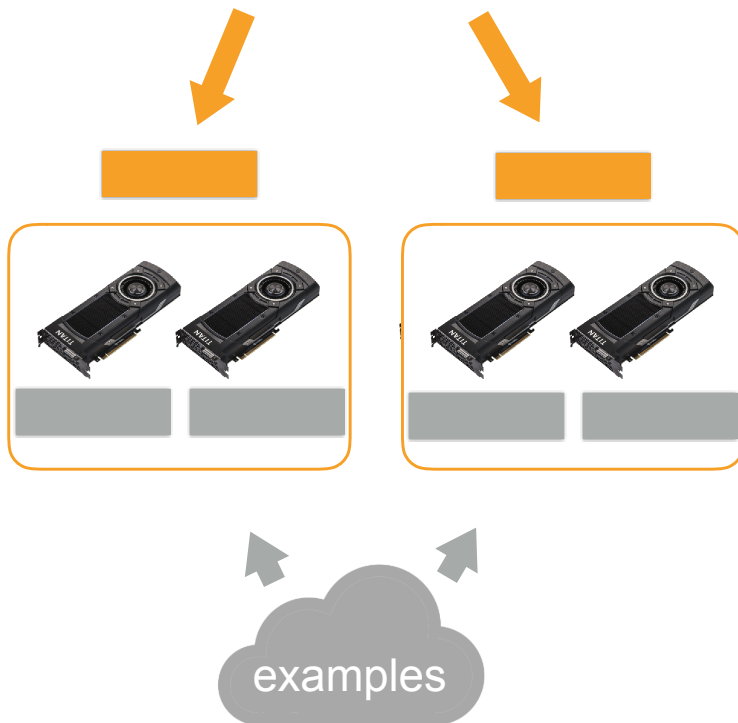


Iterating a Batch

- Further split and move to each GPU

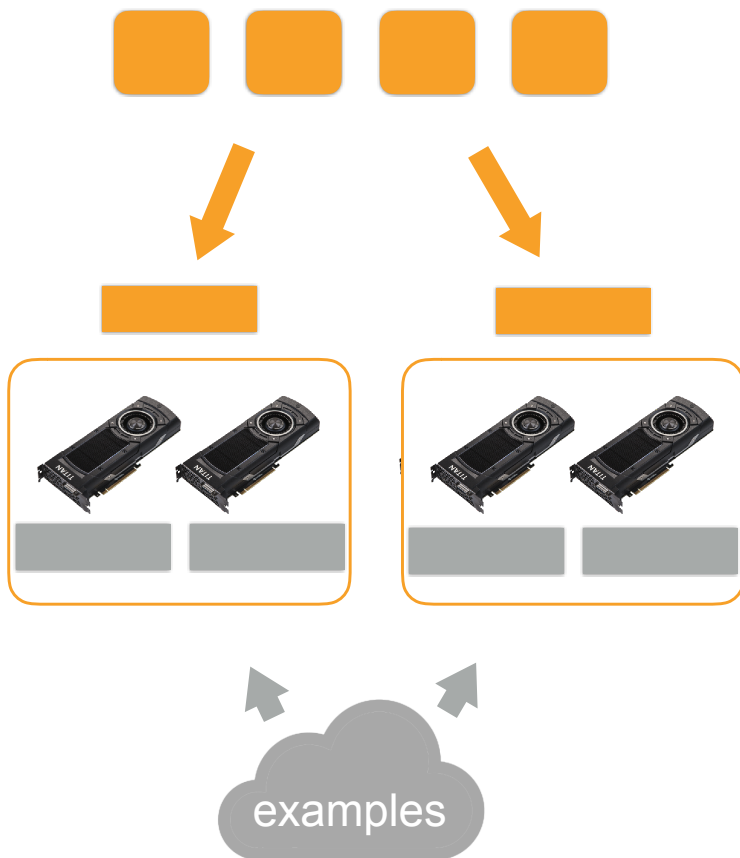


Iterating a Batch



- Each server maintain a part of parameters
- Each worker pull the whole parameters from servers

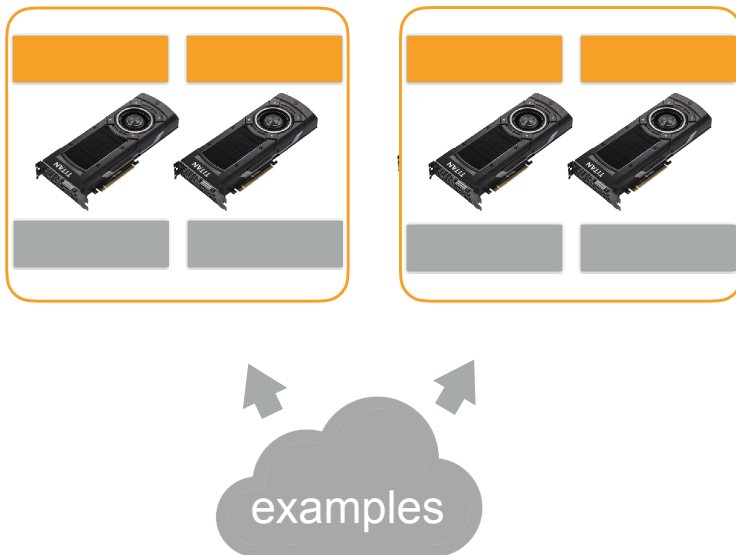
Iterating a Batch



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- Each worker pull the whole parameters from servers

Iterating a Batch

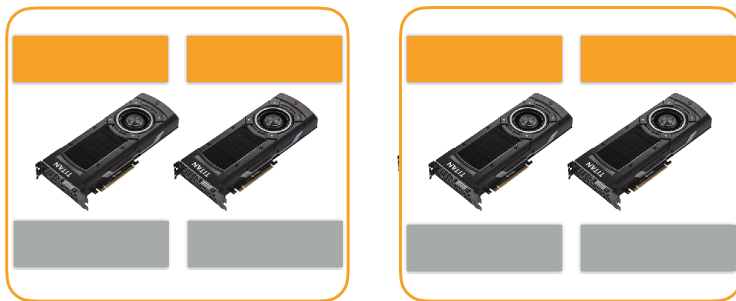
- Copy parameters into each GPU



Iterating a Batch

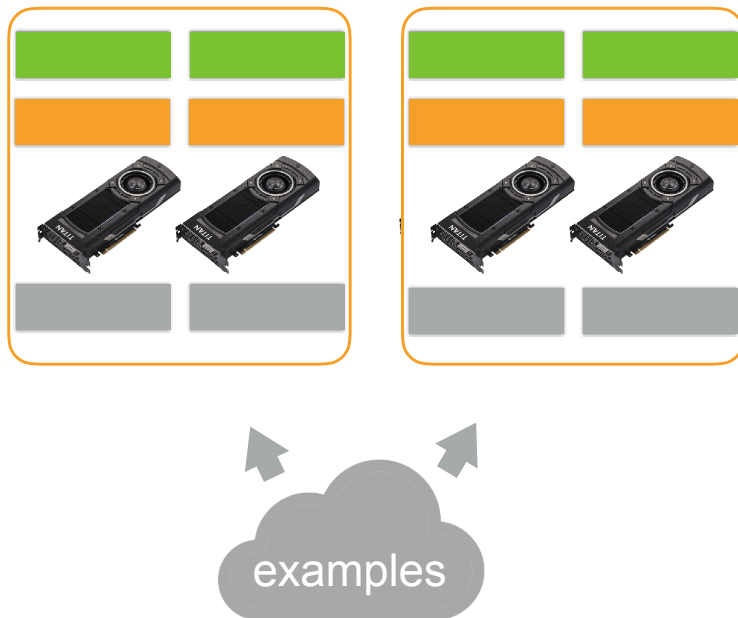


- Copy parameters into each GPU

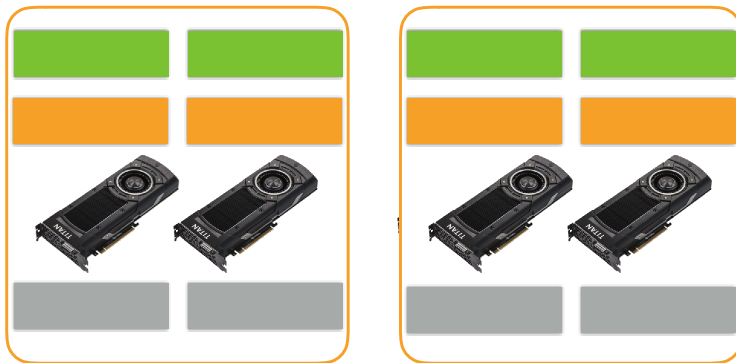


Iterating a Batch

- Each GPU computes gradients

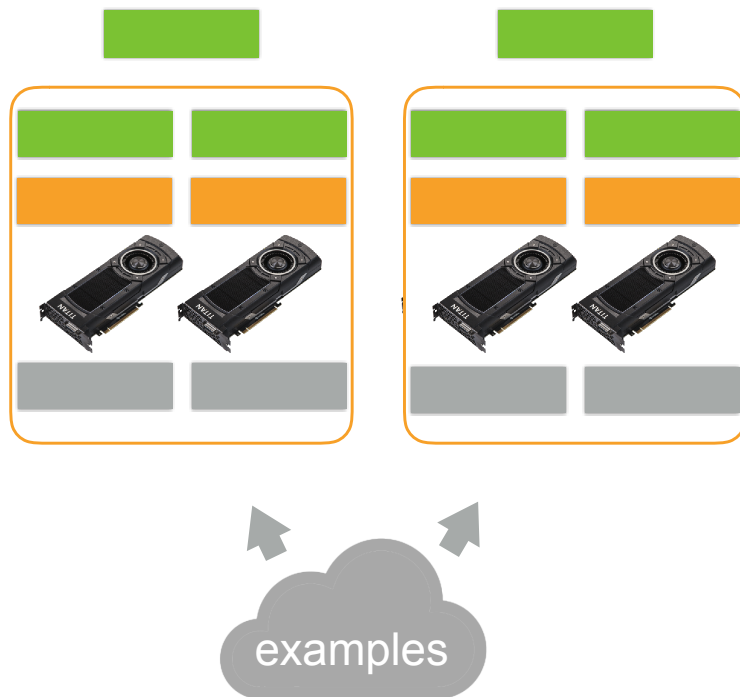


Iterating a Batch



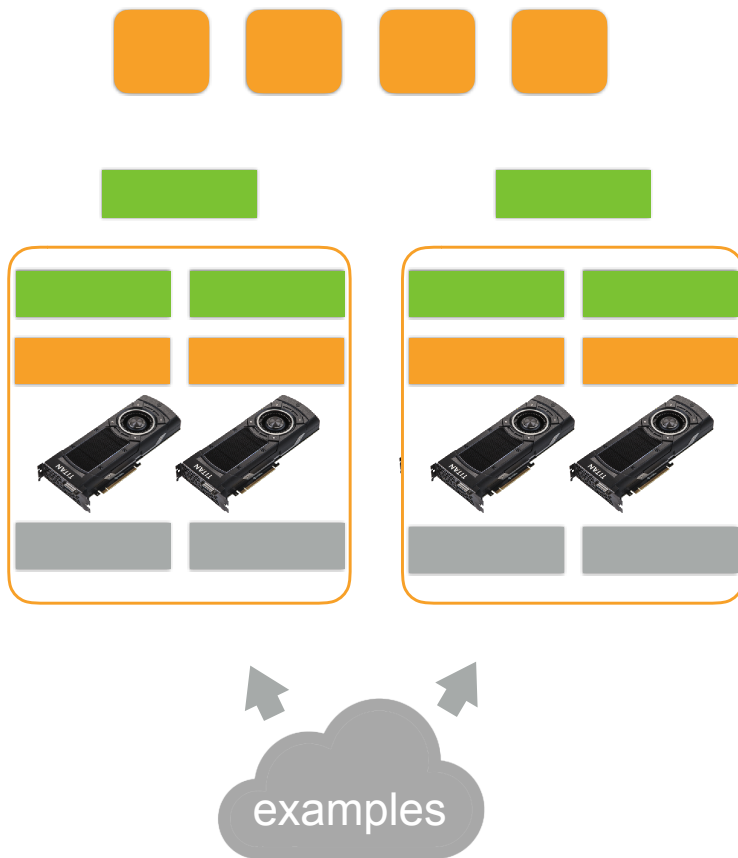
- Each GPU computes gradients

Iterating a Batch



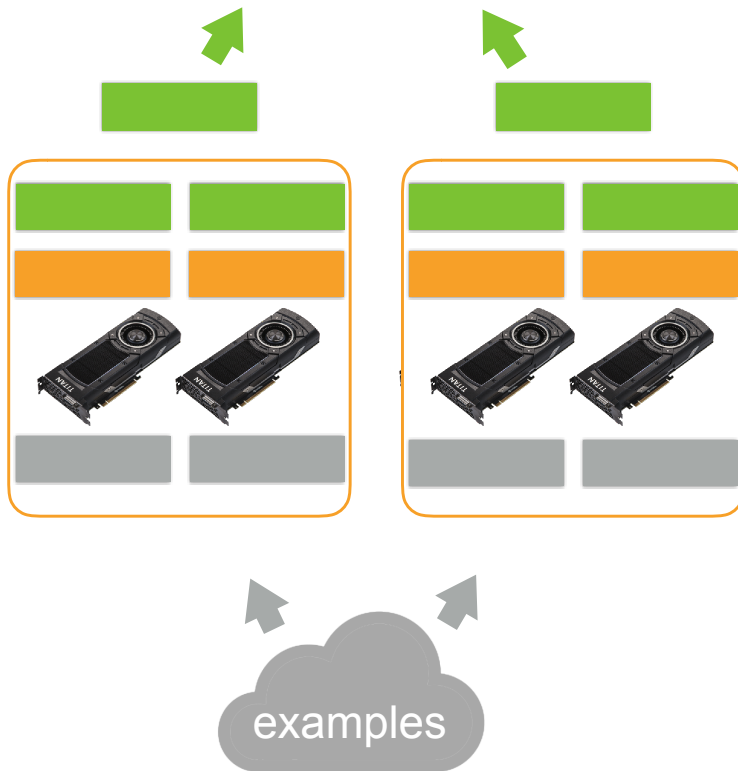
- Sum the gradients over all GPU

Iterating a Batch



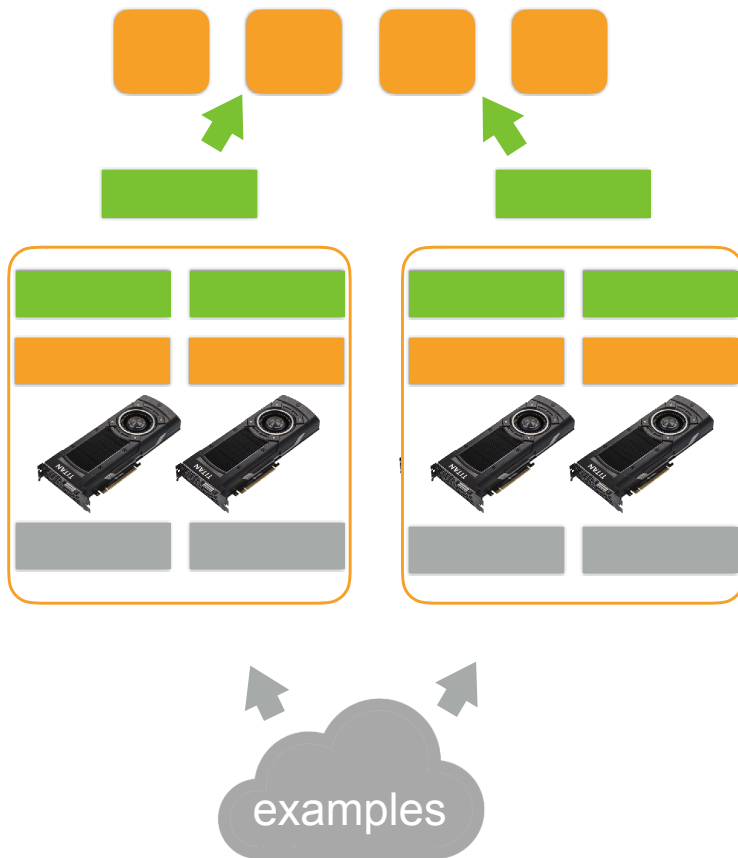
- Sum the gradients over all GPU

Iterating a Batch



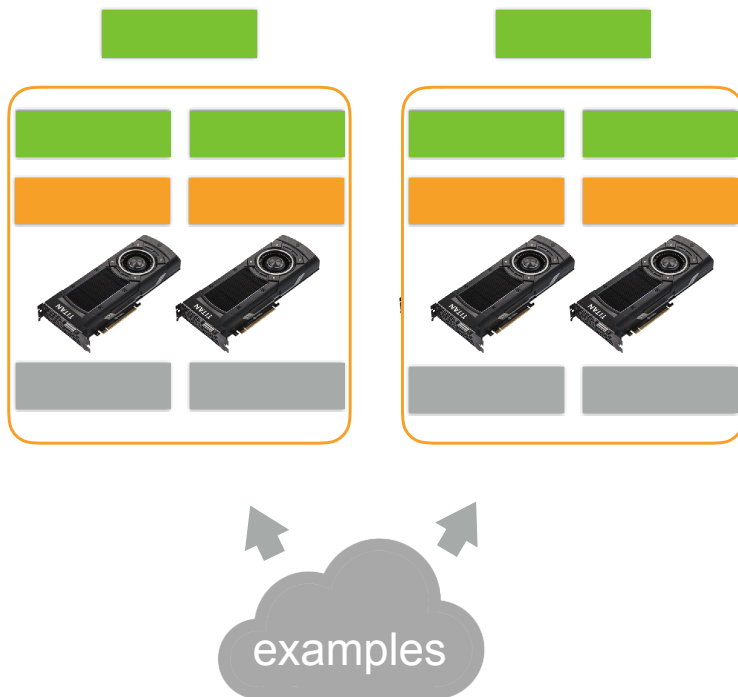
- Push gradients into servers

Iterating a Batch



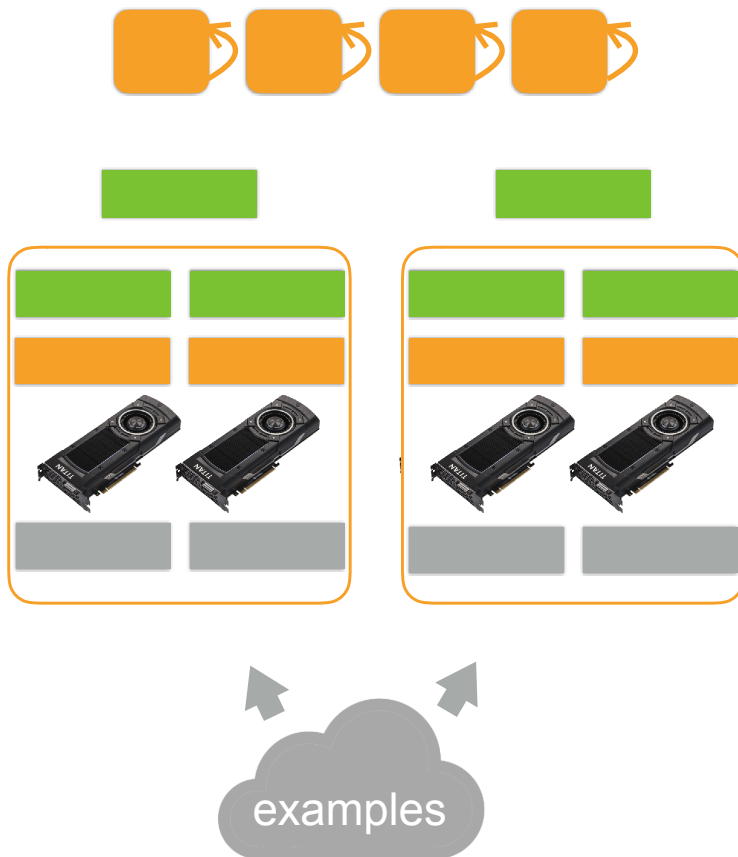
- Push gradients into servers

Iterating a Batch



- Each server sum gradients from all workers, then updates its parameters

Iterating a Batch



- Each server sum gradients from all workers, then updates its parameters

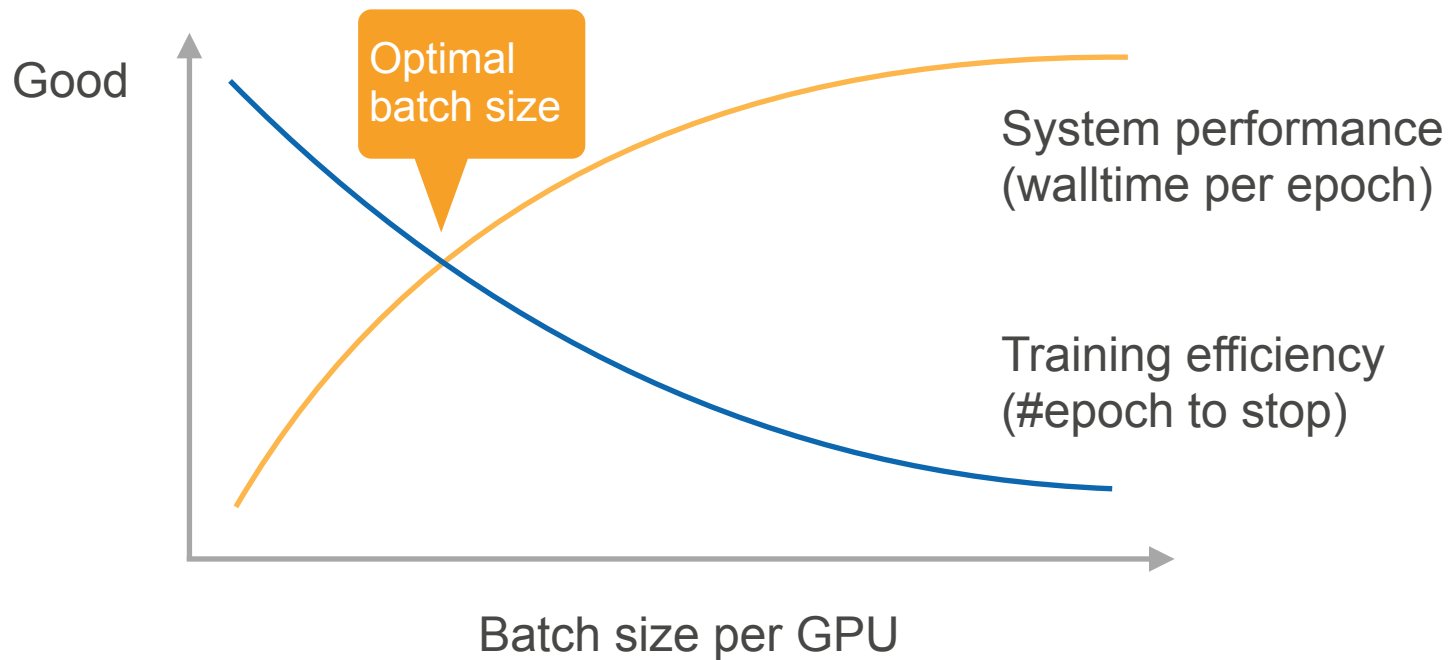
Synchronized SGD

- Each worker run synchronically
- If n GPUs and each GPU process b examples per time
 - Synchronized SGD equals to mini-batch SGD on a single GPU with a nb batch size
- In the ideal case, training with n GPUs will lead to a n times speedup compared to a single GPU training

Performance

- $T1 = O(b)$: time to compute gradients for b example in a GPU
- $T2 = O(m)$: time to send and receive m parameters/ gradients for a worker
- Wall-time for each batch is $\max(T1, T2)$
 - Idea case: $T1 > T2$, namely using large enough b
- A too large b needs more data epochs to reach a desired model quality

Performance Trade-off



Practical Suggestions

- A large dataset
- Good GPU-GPU and machine-machine bandwidth
- Efficient data loading/preprocessing
- A model with good computation (FLOP) vs communication (model size) ratio
 - ResNet > AlexNet
- A large enough batch size for good system performance
- Tricks for efficiency optimization with a large batch size

Multi-GPU Notebooks

Image Augmentation

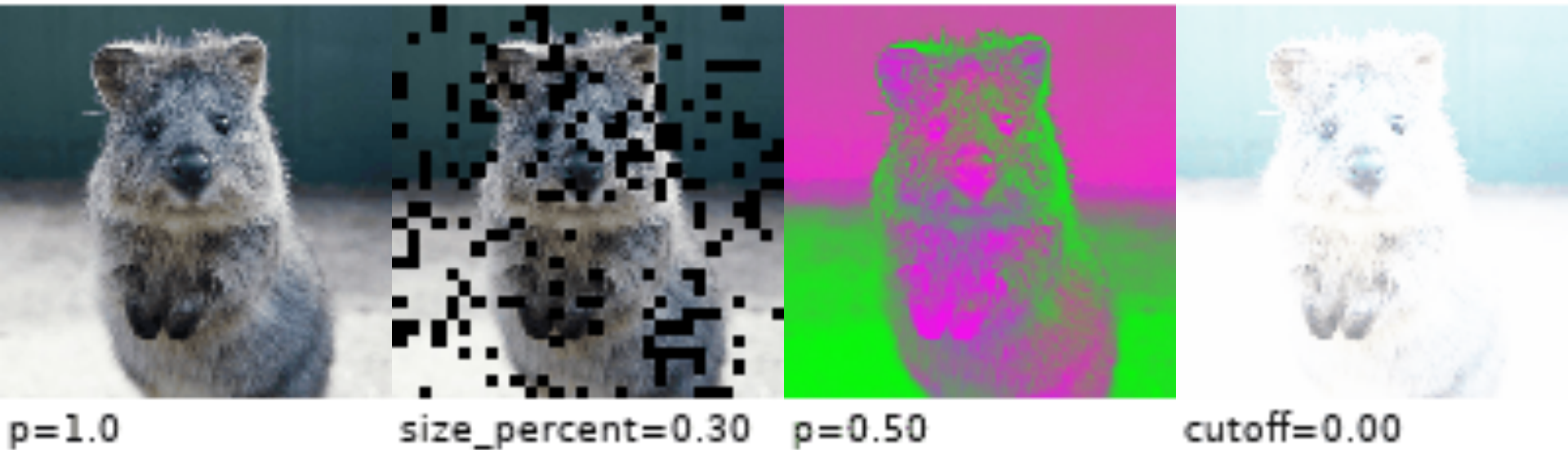
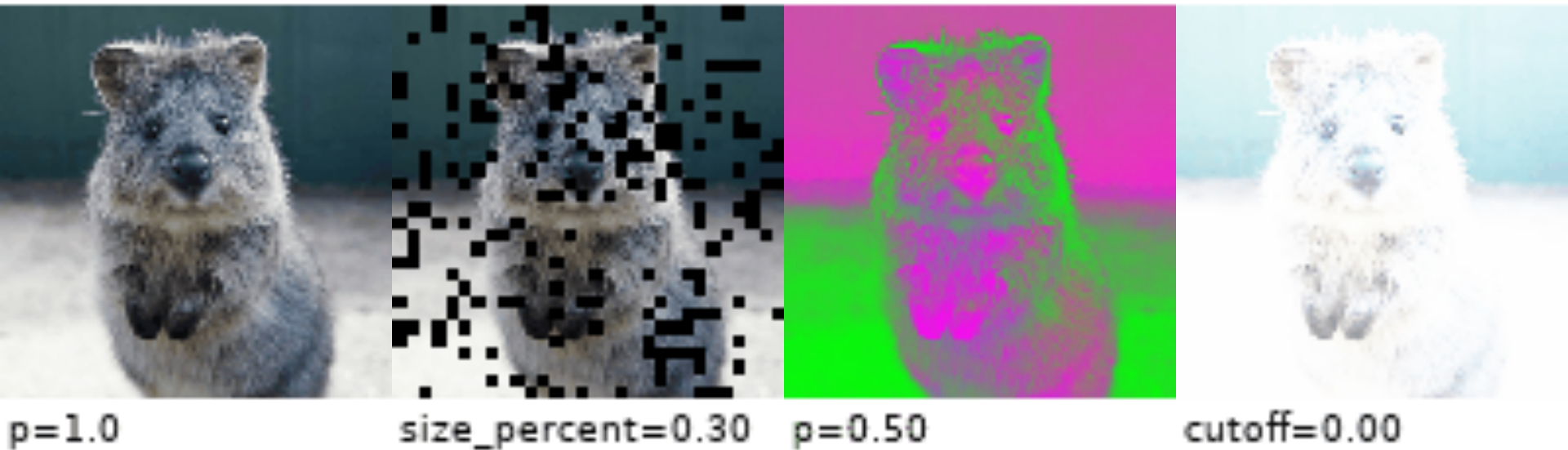


Image Augmentation



Real Story from CES'19

- Startup with smart vending machine demo that identifies purchases via a camera
- Demo at CES failed
 - Different light temperature
 - Light reflection from table
- The fix
 - Collect new data
 - Buy tablecloth
 - Retrain all night



Data Augmentation



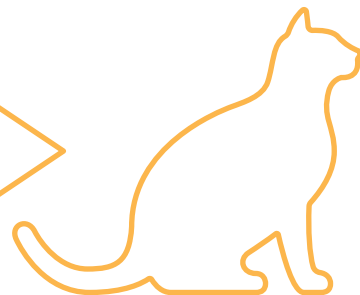
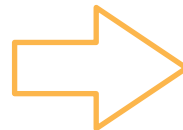
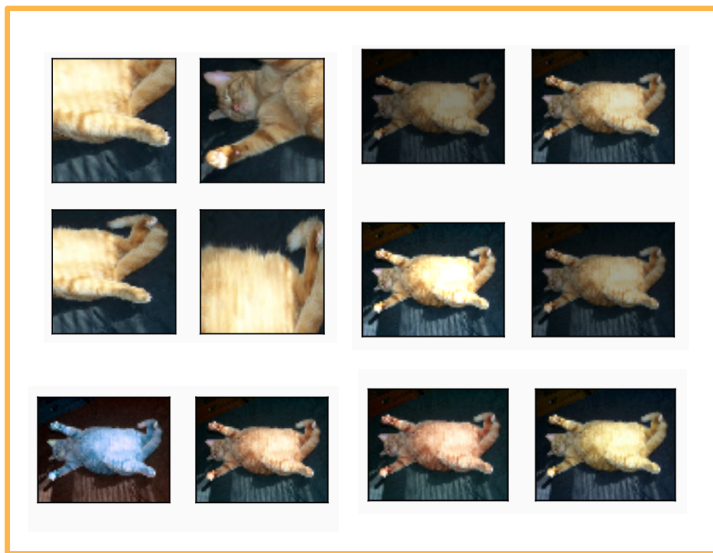
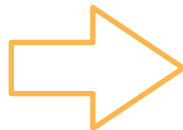
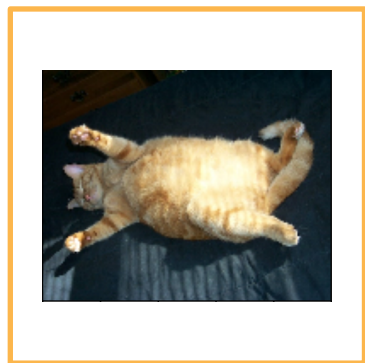
- Use prior knowledge about invariances to augment data
 - Add background noise to speech
 - Transform / augment image by altering colors, noise, cropping, distortions

Training with Augmented Data

Original

Augmented Dataset

Model



Generate on the fly

Flip

vertical

horizontal



Flip

vertical



horizontal



Flip

vertical



horizontal



Crop

- Crop an area from the image and resize it
 - Random aspect ratio (e.g. [3:4, 4:3])
 - Random area size (e.g. [8%, 100%])
 - Random position



Crop

- Crop an area from the image and resize it
 - Random aspect ratio (e.g. [3:4, 4:3])
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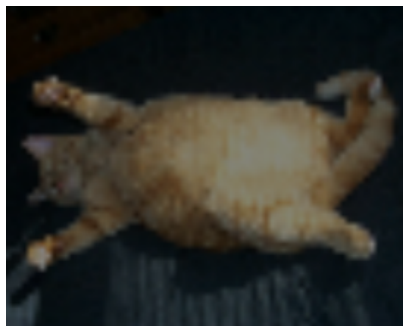
Color

Scale hue, saturation, and brightness (e.g. [0.5, 1.5])



Color

Scale hue, saturation, and brightness (e.g. [0.5, 1.5])



Brightness

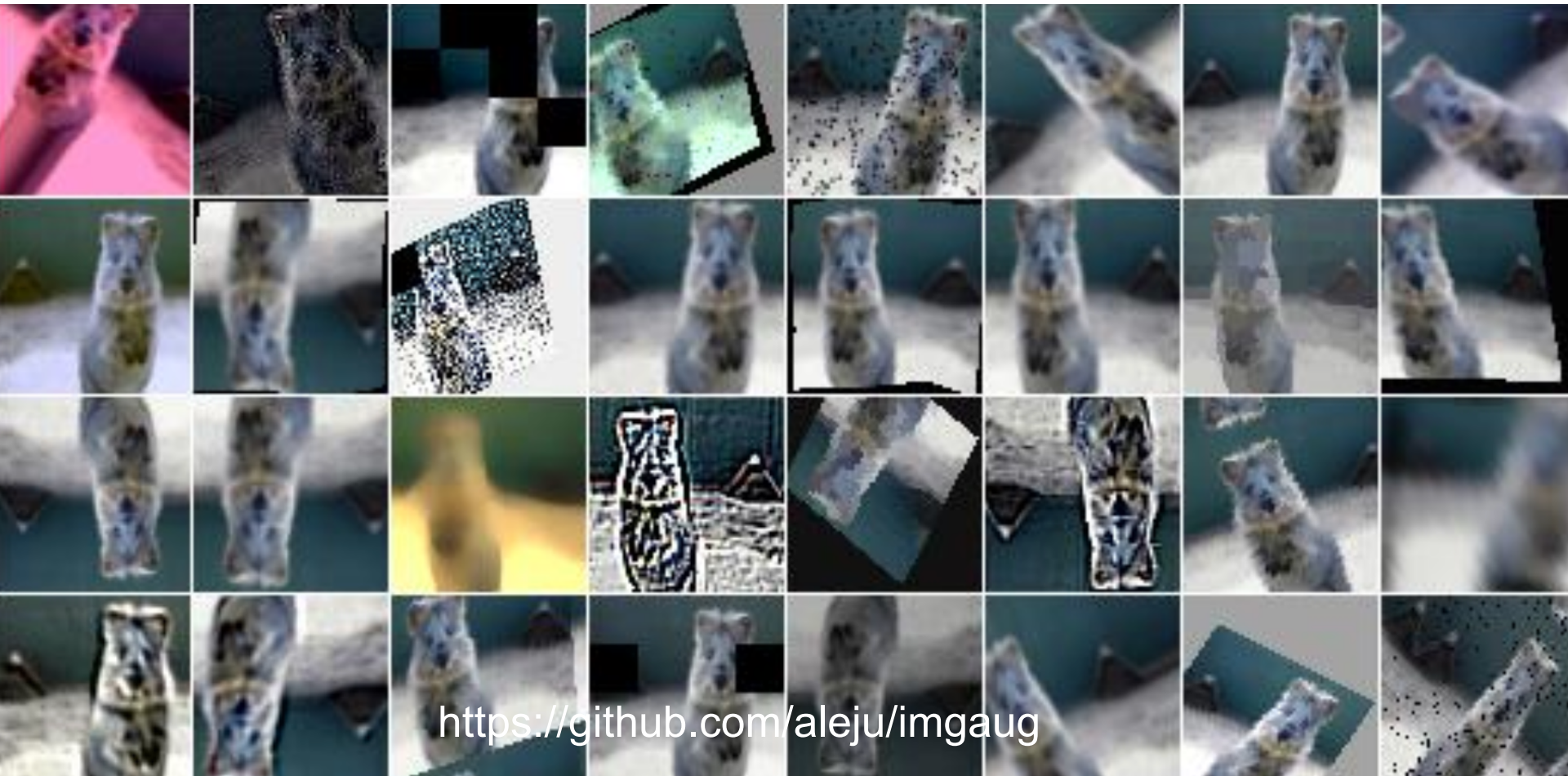


Hue

Many Other Augmentations



Many Other Augmentations



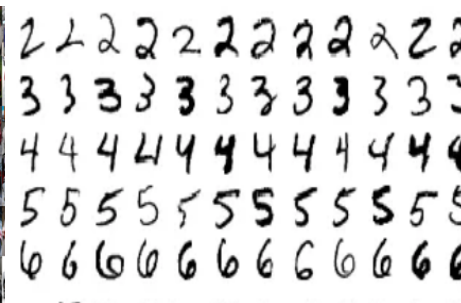
<https://github.com/aleju/imgaug>



Fine Tuning

Labelling a Dataset is Expensive

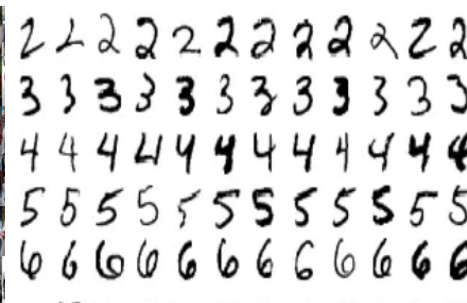
# examples	1.2M	50K	60K
# classes	1,000	100	10



My dataset

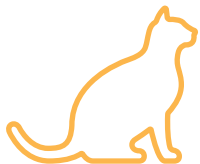
Labelling a Dataset is Expensive

# examples	1.2M	50K	60K
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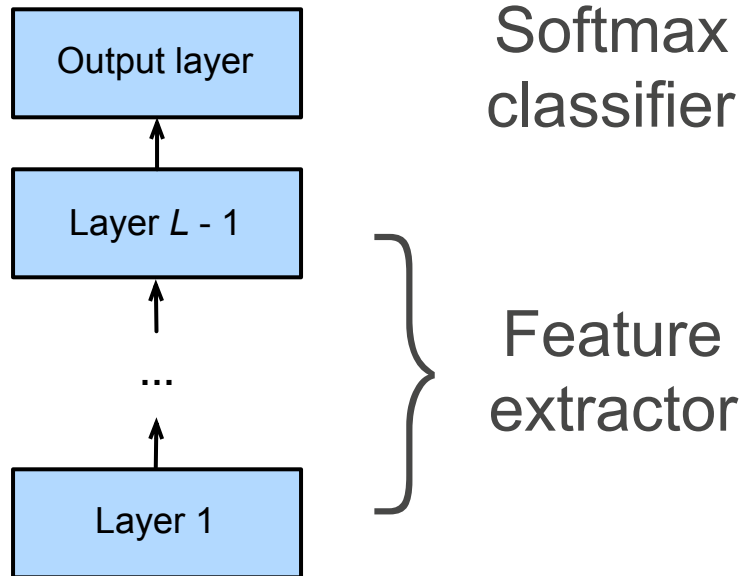


Can we
reuse this?

My dataset



Network Structure

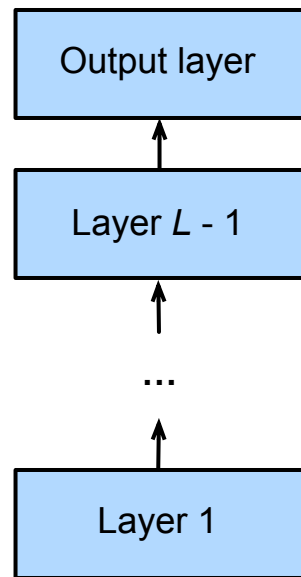


Two components in deep network

- **Feature extractor to map raw pixels into linearly separable features.**
- Linear classifier for decisions



Fine Tuning

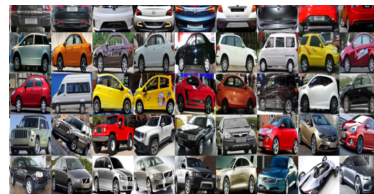


Don't use last layer
since classification
problem is different



Likely good feature
extractor for target

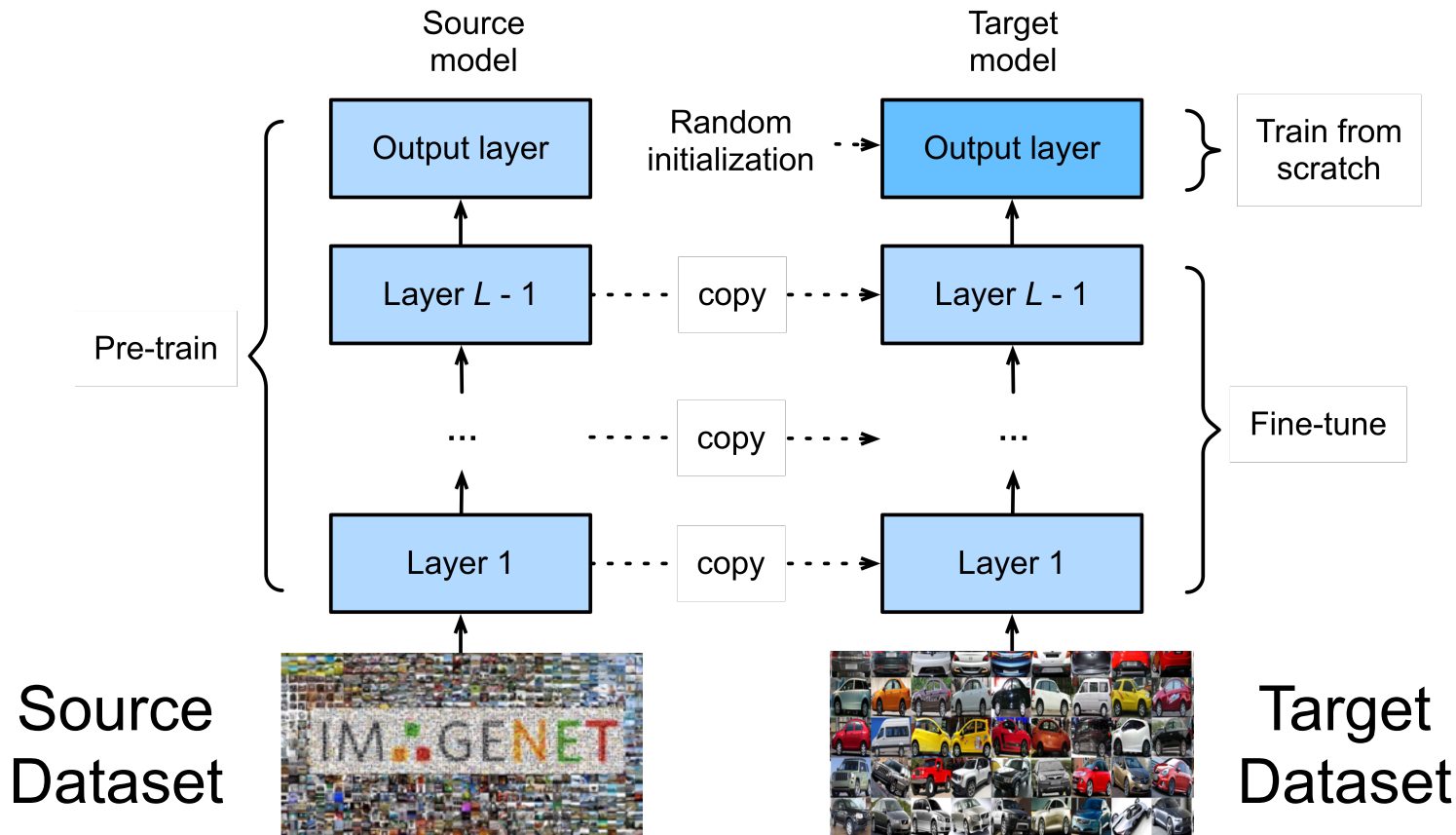
Source
Dataset



Target
Dataset

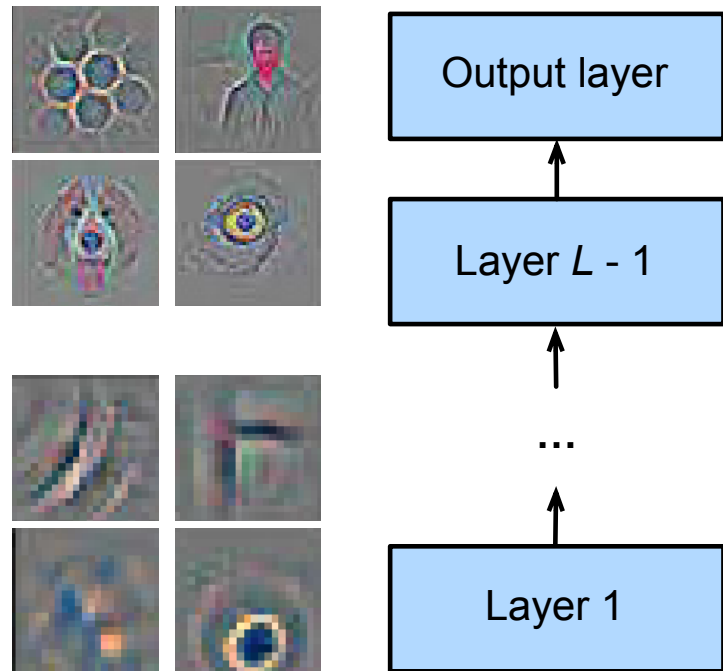


Weight Initialization for Fine Tuning



Fix Lower Layers

- Neural networks learn hierarchical feature representations
 - Low-level features are universal
 - High-level features are more related to objects in the dataset
- **Fix the bottom layer parameters during fine tuning**
(useful for regularization)



Re-use Classifier Parameters

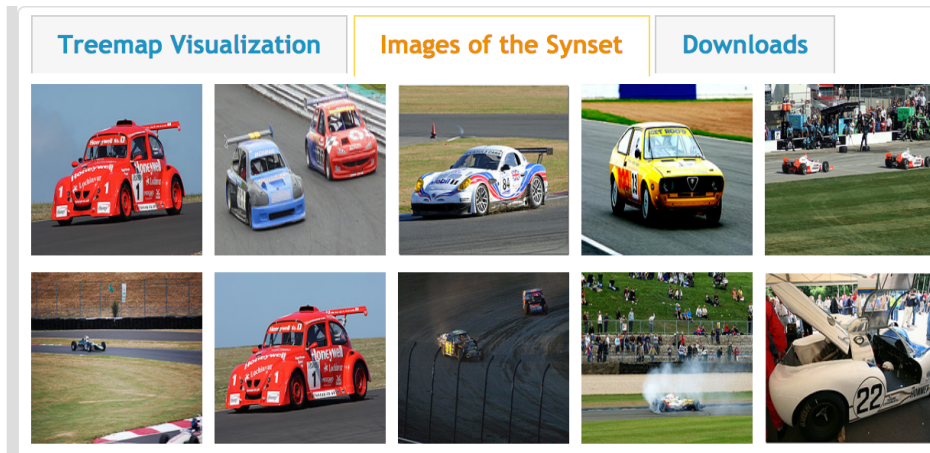
Lucky break

- Source dataset may contain some of the target categories
- Use the according weight vectors from the pre-trained model during initialization



Racer, race car, racing car

A fast car that competes in races



Fine-tuning Training Recipe

- Train on the target dataset as normal but with strong regularization
 - Small learning rate
 - Fewer epochs
- If source dataset is more complex than the target dataset, fine-tuning can lead to better models (source model is a good prior)

Fine-tuning Notebook

Summary

- To get good performance:
 - Optimize codes through hybridization
 - Use multiple GPUs/machines
- Augment image data by transformations
- Train with pre-trained models